#### Pimpri Chinchwad Education Trust's PIMPRI CHINCHWAD COLLEGE OF ENGINEERING SECTOR NO. 26, PRADHIKARAN, NIGDI, PUNE 411044



#### STRUCTURE FOR THIRD YEAR B. TECH SEM-III (E&TC ENGINEERING)

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		B.TECH Semester-V												
Course Code	Course Type	Course Name				Teachin Scheme	e	end	Evaluation Scheme					
		56		Р	Т	Hours	Credits	CE	MTE	ЕТЕ	TW	PR	OR	Total
BET5414	PCC	Control System	2		1	3	3	20	30	50				100
BET5415	PCC	Digital communication	3	1		3	3	20	30	50				100
BET5416	PCC	Digital communication Lab		2		2	1				25	25		50
BET5417	PCC	Project Based Learning-V	Br	2)	q!	s F2ee	don)"				50			50
BET55xx	PEC	Program Elective-I	2			2	2	20	30	50				100
BET55xx	PEC	Program Elective-I Lab		2		2	1				25	25		50
BET55xx	PEC	Program Elective-II	2			2	2	20	30	50				100
BET55xx	PEC	Program Elective-II Lab		2	þŝ	2	1				25		25	50
BET56xx	OEC	Open Elective-II	3			3	3	20	30	50				100
	HSMC	HSMC-5	1			1	2	30		20				50
	MC- ES/PDT	MC-ES/PDT		2		2								0
BET59XX	PFC	PFC		2		2								0
	AC	AC		1		1								0
Total			14	13	1	28	19							750

#### List of Program Elective-I (Code:BET55xx)

Course Code	Course Name	
BET5501	Power Electronics	
BET5502	Power Electronics Lab	
BET5503	Advanced Microcontroller	Choose any one
BET5504	Advanced Microcontroller Lab	
BET5505	Multidimensional Signal Simulation	
BET5506	Multidimensional Signal Simulation Lab.	
BET5507	Information Theory and Coding	
BET5508	Information Theory and Coding Lab.	
BET5509	Object oriented programming	
BET5510	Object oriented programming Lab.	

# List of Program Elective-II (Code:BET55xx)

Course Code	Course Name	
BET5511	Robotronics and Automation	
BET5512	Robotronics and Automation Lab.	
BET5513	Digital Design with Verilog HDL	Choose any one
BET5514	Digital Design with Verilog HDL Lab.	
BET5515	Digital Image processing	
BET5516	Digital Image processing Lab.	
BET5517	Antenna & wave Propagation	
BET5518	Antenna & wave Propagation Lab.	
BET5519	Computational Tools for Data Analytics	
BET5520	Computational Tools for Data Analytics Lab.	

# List of Open Elective-II (Code:BET56xx)

Course Code	Course Name	
BET5601	Smart City: An Electronic Perspectives	Choose envione
BET5602	Modeling and Simulation with MATLAB	Choose any one

#### List of Proficiency Courses (BET59xx)

Course Code	Course Name	
BET5911	Basics of Lab View	
BET5912	MATLAB Scripting	Choose any one
BET5913	Embedded Product Design	•
BET5914	Model based Development using MATLAB	
BET5915	PCB Design Skill	



Optimism Excellence

# **Course Syllabus**

# T.Y. B.Tech. Semester-V

<b>Program:</b>	B. Tech.	(E&TC)				Semester:	V
Course:	Control	Systems			(	Code:	BET5414
Teaching Scheme			Evaluation Scheme				
Lecture	Practical	Tutorial	Credit	IE	MTE	ETE	Total
2	-	1	3	20	30	50	100

#### **Prior Knowledge of:**

1. Integral Transforms and Partial Differential Equations. Applied Mathematics Is essential

#### **Course Objectives:**

1. To Introduce elements of control system and their modeling using various Techniques.

2. To get acquainted with the methods for analyzing the time response and Stability of System.

3. To Introduce and analyze the frequency response and Stability of System.

4. To Introduce concept of root locus, Bode plots, Nyquist plots.

#### **Course Outcomes:**

At the end of Course the students will be able to:

#### "Knowlege Brings Freedom"

1. CO1: Determine and use models of physical systems in forms suitable for use in the analysis and design of control systems.

2. CO2: Determine the absolute stability of a closed-loop control system.

3. CO3: Perform time domain analysis of control systems required for stability analysis.

4. CO4: Perform frequency domain analysis of control systems required for stability analysis.

Detail	ed Syllabus:	
Unit	Description	Duration
1.	<ul> <li>Introduction to Control Systems &amp; its modeling:</li> <li>Basic Elements of Control System, Open loop and Closed loop systems, Differential equations and Transfer function.</li> <li>Modeling of Electric systems, Translational and rotational mechanical</li> </ul>	6
2.	systems. Block diagram reduction Techniques. Signal flow graph         Time domain analysis:         Time domain analysis: transient response and steady state response, standard test inputs for time domain analysis, order and type of a system.	5

	Transient analysis of first and second order systems. Time domain specifications of second order under damped system from its step response.	
	Steady state error and static error constants	
3.	Stability analysis:	
	Characteristic equation of a system, concept of pole and zero, response of various pole locations in s-plane, concept of stability absolute stability, relative stability, stability of system from pole locations.	6
	Routh Hurwitz stability criterion.	
	Root locus: definition, magnitude and angle conditions, construction of root locus, concept of dominant poles, effect of addition of pole and zero on root locus. Application of root locus for stability analysis.	
4.	Frequency domain analysis:	
	Frequency response and frequency domain specifications. Correlation between time domain and frequency domain specifications. Polar plot. Nyquist stability criterion and construction of Nyquist plot. Bode plot, determination of frequency domain specifications and stability analysis using Nyquist plot and Bode plot. Introduction to state space representation. Advantages.	7
	Total	24
Text ]	"Knowlege Brings Freedom" Books:	

1. N. J. Nagrath and M. Gopal, "Control System Engineering", New Age International Publishers, 5 th Edition, 2014

2. K. Ogata, "Modern Control Engineering", Prentice Hall India Learning Private Limited; 5th Edition, 2014

#### **Reference Books:**

- 1. Benjamin C. Kuo, "Automatic control systems", Prentice Hall of India, 8th Edition,2007.
- 2. M. Gopal, "Control System Principles and Design", Tata McGraw Hill, 4th Edition, 2008.
- 3. Schaum's Outline Series, "Feedback and Control Systems" Tata McGraw-Hill,2000

#### **MOOC / NPTEL Courses:**

1. NPTEL Course "Control System"

https://nptel.ac.in/courses/107/106/107106081/

2. NPTEL Course "Control System Design"

https://nptel.ac.in/courses/115/108/115108104/

#### List of Tutorials:

- 1. Numericals on Block diagram reduction technique.
- 2. Numericals on Signal Flow Graphs.
- 3. Computation of transfer function of Electric Circuits, Mechanical Circuits Force-Voltage and Force Current analogy
- 4. Time domain specifications of the given system.
- 5. Steady state error and error coefficients of the type 0, 1 and 2 systems for step, ramp and parabolic inputs.
- 6. Stability analysis using Routh Hurwitz Criterion.
- 7. Computation of root locus for given G(s)H(s).
- 8. Frequency domain specifications of the system.
- 9. Computation of frequency response analysis using Bode Plot for given G(s) H(s).
- 10. Frequency response analysis using Nyquist Plot

-Program:B. Tech. (E&TC)					Semester: V			
Course: Digital Communication Code						Code: BET5415		
Teachin	g Scheme			Evaluatio	on Scheme	•	-	
Lecture	e Tutorial	Credit	Hours	IE	MTE	ETE	Total	
03		03	03	20	30	50	100	
Prior kn Signals a	owledge of and Systems Mod	ulation Tech	niques are e	essential				
Signais	ind bysteinis, wou		inques ure e					
Objectiv	ves:		1					
2. T te 3. T te <b>Outcom</b> After lea CO1. Apj CO2. Ana CO3. An CO4. Em & bit erro CO5. Exa system.	o introduce the s chniques. o Familiarize the chniques es: rning the course, t oly the knowledge alyze the workin alyze the perform phasize on perfo or probability. mine the performs	tudents with students wi the students se of wavefor ag of baseba nance of baseba prmance of p ance of the d	th the conce th the conce should be at m coding t nd digital t seband reco bass band c bass band c	ept of Pass epts of spre- ble to: echniques transmissio eiver syste ligital com bunication s	and compare the spectrum a spectr	tion and der and multiuse heir perform e of noise. ystems in te iltiuser radio	nodulation r communication ance. rms of bandwidth communication	
		ommunicatio	in system w	itii spread s	peeu uni comm			
Detailed	Syllabus:		80	1000			Durotion	
	Discription Disital Transm	ission ·- Intro	duction to	Digital Co	mmunication 9	System	Duration	
1	PCM Generation	n and Rec	onstruction	. Ouantiza	tion Noise.N	on-uniform		
	Quantization and	l Compandi	ng, PCM	with noise	: Decoding r	noise, Error		
1	threshold, Delta	Modulation	n, Adaptiv	e Delta M	Iodulation, D	elta Sigma		
	Modulation, Diff	ferential Pul	lse Code M	Modulation	. Line Codes	s and their	<b>.</b>	
	power spectra.						07	
2	Multiplexing &	Synchroni	zation Tec	hniques:-				
-	Digital Multiple	xing: Multi	plexers ar	nd hierarcl	nies, Data M	lultiplexers,	05	
	synchronization:	BitSy	nchronizat	ion,	Scramblers,	Frame	05	
	Synchronization.	inter-symbol	i interferen	ce,Equaliza	uion.			
3	Baseband De	etection Tec or Test 9	chniques:- Signal spe	Detection	Theory: M.	AP, LRT, Geometric		
	representation o	f signal, Lik	kelihood fu	nctions, C	ptimum Filter	, Matched	06	
	Filter, Probabilit	ty of Error o	f Matched	Filter, Corr	elation receive	er.		

4	Digital Passband Modulation Techniques:- Pass band transmission model,	
	Generation and Detection of Coherent system (BASK, BFSK, BPSK, QPSK,	
	MSK) and their error probability ,Generation and detection of - M-ary PSK,	07
	M-ary QAM and their error probability.	07
5	Multiuser radio communication:- Multi access techniques: TDMA & CDMA	
	wireless communication systems, Multicarrier communications: OFDM -	
	modulation and demodulation, spectral characteristics, bit and power allocation.	05
6	Spread Spectrum Communications: - Introduction, Pseudo noise sequences,	
	A notion of spread spectrum, Direct sequence spread	
	spectrum with coherent BPSK, Signal space dimensionality & processing gain, Probability of error, Concept of jamming, Frequency hop spread spectrum and its types.	06
	Total Hrs.	36

1. Simon Haykin, "Digital Communication Systems", 'Wiley, an Indian adaption Edition.2021

2.B.P. Lathi, Zhi Ding, "Modern Analog and Digital Communication System", Oxford University Press, 4th Edition, 2018

#### **Reference Books:**

**1.**Bernard Sklar, Fred Harris, "Digital Communications Fundamentals and Applications", Pearson Education, 3<sup>rd</sup> Edition, 2021.

2. J. G. Proakis and M. Salehi, Digital Communications, McGraw-Hill, 5<sup>th</sup> edition, 2014

**3.** A.B Carlson and P.B. Crilly, "Introduction to Digital Communication", McGraw-Hill, 5<sup>th</sup> edition, 2015

#### NPTEL Course on "Digital Communications"

Link of the Course: https://nptel.ac.in/courses/108/102/108102096/

Program: B. Tech. (E&Tc)				Semester :V					
Course : Di	gital Commun	ication Lab			Code : BET5416				
Teaching Sci	heme			Evaluation Scheme					
Lecture	Practical	Tutorial	Credit	TW	OR	PR	Total		
	02		1	25		25	50		
Prior knowl	Prior knowledge of:								
Signals and S	Systems, Modul	lation Techniq	ues are essent	ial					
<b>Objectives:</b>									
<ol> <li>To Fa digita</li> <li>To int</li> </ol>	miliarize the st l modulation t roduce students	tudents with k techniques. s the performat	ey modules on nce of Spread	of digital comm	unication system ques and use of s	ms with an em oftware tools.	phasis on		
Outcomes: At the end of 1. Apply bandw 2. Descr 3. Analy	<ul> <li>Outcomes:</li> <li>At the end of Laboratory work, the students will be able to: <ol> <li>Apply the knowledge of fundamental communication systems to interpret the parameters, such as bandwidth and data rate, etc.</li> <li>Describe and demonstrate the performance of passband communication systems.</li> <li>Analyze digital modulation techniques by using software tools.</li> </ol> </li> </ul>								
General Gui GROUP-A a	delines: Any H my 6 and GRC	Eight Experin DUP-B any 2	ents is to be	performed.					
Evnt No	List of Europ	imonto	Deta	aned Synabus:		Tel 1			
Expt. No.	List of Exper	iments		GROUP.	Δ	E			
1	Experimentel	study of DCM	and common	ded DCM using '	A' low and 'U'le				
2	DM system G	onoration & d	taction: Calor	ulation of hit rate	A law all $\mu$ is	1W			
3	ADM system	Generation &	detection: Cal	lculation of bit rac	te and Bandwidt	h.			
4	Experimental	study of line	codes and the	ir Spectral analy	sis.				
5	BPSK Genera	tion & detection	on: calculation	n of BW, observ	vation of constel	llation diagran	n and coherent		
6	BFSK Genera detection.	tion & detection	on: calculation	n of BW, observ	vation of constel	llation diagran	n and coherent		
7	QPSK Genera detection.	tion & detection	on: calculation	n of BW, observ	vation of conste	llation diagran	n and coherent		
8	DS-SS with B processing gai	PSK Generation	on & detection t detection.	n :Generation of	PN sequence usi	ing N-bit, calcu	lation of		
				GROUP-	В				
1	Implementat	ion of PCM s	ystem using	software tools					
2	Implementat	ion of BPSK	system using	g software tools					
3	Simulation st	tudy of const	ellation diag	ram of QPSK r	nodulated signa	1.			
4	Implementat	tion of OFDN	I signal gene	eration using so	ftware tools				

#### **Reference Books:**

**1.**Bernard Sklar, Fred Harris, "Digital Communications Fundamentals and Applications", Pearson Education, 3<sup>rd</sup> Edition, 2021.

- 2. J. G. Proakis and M. Salehi, Digital Communications, McGraw-Hill, 5th edition, 2014
- 3. A.B Carlson and P.B. Crilly, "Introduction to Digital Communication", McGraw-Hill, 5th edition, 2015

#### Virtual LAB Links:

1. Link: <u>https://www.etti.unibw.de/labalive/index/digitalmodulation/</u>

2. Link: https://vlab.amrita.edu/index.php?sub=59&brch=163&sim=262&cnt=970



Program: B. Tech. (E&Tc)			Semester: V Code:BET5417				
Course: Project Based Learning-V							
Teaching Scheme Evaluation Scheme							
Practica	l Tutorial	Credit	Hours	TW	OR	PR	Total
2	-	1	2	50	-	-	50
Prior kno <sup>v</sup>	wledge of:					1	
1. Mie 2. Ele	crocontroller a ctronics Circu	and I/O inte iit design	erfaces				
is essentia							
Objectives	5: Niectives:						
2. To 3. To	encourage stu introduce fun	dents to de damental st	velop viable so teps in the prote	olutions using mu otype developme	ultidisciplinary a	approach	
<ol> <li>For bas</li> <li>Ap to e</li> <li>Demonstrimember.</li> </ol>	mulate a appred on current ply previously evaluate the its rate good pres	copriate pro trends and y acquired l s quality . entation an	blem statemen societal needs. knowledge. of d writing skills	t by conducting electronics to de , develop ability	literature survey sign a prototype to work as an in	y and propose a e and Conduct ndividual and a	a viable solution experimentation as a team
Unit	Description				90		Duration
	The project s	election:	DIE	6-101:	1		24 Hrs
	Project Selectind advancements The spectrum of Automobile performance of Emphasis show he existing sy application	on should l in the exist of the proje , Health, Er of the same uld be gives stem OR inc	be based on Re ting technology ect verticals can hergy, Transpo- is going to be on in the impler cremental softw	-engineering cor y or operations. n be and not limi rtation, Security a evaluated based of nentation of hard ware advancemen	ted to industries and Consumer E on technical out dware related in its in an applicat	ice incrementations in the domain Electronics. The comes. nprovements in tion/data driver	
	Project Imple	ementation	:				
	Hardware pro nterfacing to Arduino/ Rasp The project levelopment, The project wi	ocessing un auxiliary/ oberry Pi ca with the data proces ith hardwar	nit should be peripherals. And be used to act software enhats sing and data hand be enhancement	any microcont Additionally pro chieve functional ancement shoul andling unit with should be demo	roller – Atmeg ototype develop ities in the proje d demonstrate n interfacing to a onstrated on the	ga, AVR with oment board – ect. UI/dashboard appropriate I/O PCB.	1 - 1

#### General Guidelines-

Project group shall consist of not more than 3 students per group.

Project report should address technical parameter/s analysis and/or optimization of static/dynamic characteristics or power analysis or software performance parameters. All activities are required to be recorded in logbook.

A regular assessment of PBL work is required to be maintained at the department. It is expected that the PBL log book must include following:

1. Weekly monitoring by the PBL guide,

2. Assessment sheet for PBL work review by PBL guide and PBL Evaluation Committee (PEC).

The PEC structure shall consist of Head of the department, 1/2 senior faculties of the department and one industry expert (optional). Continuous Assessment Sheet (CAS) is to be maintained by the department.

Project shall be reviewed twice during the tenure by industry expert/ senior faculty member



## **Program Elective-I**

Program:	B. Tech. (I	E&TC)					Semes	ster :	V	
Course :	Power Elec	tronics	Code:BET5501							
Teaching Scheme (Hours)					Eval	uation	Scheme	•		
Lecture	Tutorial	Practical	Credit	CE	MTE	ETE	TW	PR	OR	Total
2	-	-	2	20	30	50	-	-	-	100

#### Learner should have Prior knowledge of,

- 1. Basic electrical concepts like voltage, current, power, basic laws, Circuit/Network, etc.
- 2. Basic elements like Resistor, Capacitor and Inductor.
- 3. Semiconductor devices like Diode, BJT and MOSFET.
- 4. Mathematical concepts like Integration, Derivative, Fourier series, etc.

#### **Objectives:**

The objectives of this course are:

1. To introduce different power devices like SCR, Power MOSFET and IGBT with construction, V-I characteristics, device ratings and typical triggering/driver circuits.

2. To understand working, performance analysis and design of various power converter circuits such as ac to dc converters, inverter, chopper, and AC voltage controllers.

To introduce various applications of power converters using power devices.

#### **Outcomes:**

3.

After Successfully completing the course, the learners will be able to:

1. Differentiate based on the characteristic parameters among SCR, Power MOSFET & IGBT and identify suitability of the power device for certain applications and understand the significance of device ratings.

- 2. Analyze various power converters based on their performance parameters.
- 3. Understand the applications of power electronics.
- 4. Understand case studies of power electronics in applications like electric vehicles, solar systems etc.

Detaile	d Syllabus:	
Unit	Description	Durati on
		(Hrs)
	Unit I: Study of Power Devices	
	Construction, VI characteristics, switching characteristics of SCR, Power MOSFET and	
	IGBT, Performance overview of Silicon, Silicon Carbide & GaN based MOSFET and	
1	IGBT, Device ratings of SCR, Power MOSFET & IGBT and their significance,	06
	requirement of a typical triggering / driver (such as opto isolator) circuits for various	
	power devices, importance of series and parallel operations of various power devices	
	(no derivation and numerical), Protections to power devices.	

	Unit II: AC to DC Power Converters							
2	Concept of line & forced commutation, Single phase Semi & Full converters using SCR for R and R-L loads, its performance analysis and numerical. Effect of source inductance and freewheeling diode, Significance of power factor and its improvement using PWM based techniques, Three phase Full converters using SCR for R load and its performance analysis, Single Phase PWM Rectifier using IGBT, Three Phase Controlled Rectifier Using IGBT, Difference between SCR based conventional rectifiers and IGBT based rectifiers. Application of AC to DC converters in DC motor drive for single phase separately excited dc motor.	06						
3	Unit III: DC to AC Power Converters							
	Single phase half and full bridge square wave inverter for R and R-L load using MOSFET							
	/ IGBT and its performance analysis and numerical, Cross conduction in inverter, need of							
	voltage control and strategies in inverters, classifications of voltage control techniques,							
	control of voltage using various PWM techniques and their advantages, concept and need							
	of harmonic elimination / reduction in inverters,							
	Three Phase voltage source inverter for balanced star R load with 120 and 180 degree							
	mode of operation.							
	Applications of Inverter in Electronic Ballast, BLDC motor drive, Variable voltage &							
	variable frequency three phase induction motor drive, On-line and Off- line UPS.							
4	Unit IV: DC to DC and AC to AC Power Converters							
	<b>DC to DC Power Converters:</b> Classification of choppers, Step down chopper for R and							
	RL load and its performance analysis, Step up chopper, various control strategies for							
	choppers, types of choppers (isolated and non-isolated). Applications of DC Chopper in	06						
	DC Motor drive.							
	AC to AC Power Converter: Single phase AC Voltage Controller using IGBT & SCF							
	for R load. Application of AC Voltage controller in FAN regulator, Electric Furnace.							
	Case study of power electronics in electric vehicle and photovoltaic solar system.							
	Total	24						

M. H. Rashid, "Power Electronics Circuits Devices and Applications", PHI,4th Edition 2017 New Delhi.

2) M. D. Singh and K. B. Khanchandani, "Power Electronics", TMH, 2 nd Edition 2006.

#### **Reference Books:**

 Ned Mohan, T. Undeland & W. Robbins, "Power Electronics Converters Applications and Design, John Willey & sons, Singapore, 2 nd Edition Oxford University Press, New Delhi, 2005
 Muhammad H. Rashid , "Power Electronics Handbook", Academic Press, 2nd Edition, 2001.
 Bogdan M. Wilamowski, J. David Irwin, "The Power Electronics and Motor Drives Handbook", CRC Press, 1 st Edition, 2011. ; eBook: ISBN 9780429165627, 2019.

4) SCR Manual by GE Company

 NPTEL Course on "Power Electronics:

 Link of the Course:

 https://nptel.ac.in/courses/108/105/1081050

 66/

 https://nptel.ac.in/courses/108/102/1081021

 45/

 https://nptel.ac.in/courses/108/107/1081071

 28/

 https://nptel.ac.in/courses/108/108/1081080

 77/

 https://batteryuniversity.com



Progra	am: I	B. Tech. (I	emester: V										
Course : Power Electronics Lab									Code:BET5502				
Teach	ing S	cheme (H	ours)		Evaluation Scheme								
Lectui	re '	Tutorial	Practical	Credit	CE	MTE	ETE	тw	PR	OR	Total		
-		-	02	01	-	-	-	25	25	-	50		
Learn 1. 2. 3. 4. 5. <b>Objec</b> The ob 1. MOSF	er sh Bas Bas Ser Ma Use tives: ojectiv To	ould have sic electric sic elemen niconducto thematical e of equipr wes of this understand	Prior know al concepts I ts like Resist or devices lik concepts lik nent's such a course are: d the V-I cha	racteristic	e, curre itor, and BJT and ion, De upply, s and w ice rati	ent, powe d Inducto d MOSFI rivative, CRO, Fu	r, basic r. ET. Fourier nction (	laws, C series, Generat	Circuit/Netw etc. or, DMM, o er devices I	vork, etc	c. R, Power		
2. conver 3.	To ters, : To	understand inverter, cl understand	d the workin hopper, and a d the applica	g and perf AC voltag tions of Po	ormanc e contre ower El ge Br	e of vari ollers. ectronics	ous pov	ver conv	erter circu	its such	as ac to dc		
After S 1. their sp 2. 3.	Succe Un pecifi An Un	ssfully cor derstand tl cations. alyze vario derstand tl	npleting the ne working o ous performa ne power ele	course, the of different ince param ctronics co	e learne t power neters o onverte	ers will b devices of the diff rs used in	e able to like SC erent po variou	o: R, Powe ower co s applic	er MOSFE' nverters. eations.	Г, IGB7	Γ and also		
			Lis	t of Labo	ratory	Experin	nent						
	Gro	up A (Pov	ver Device (	Character	istics).	1 comp	lsorv.	from 2	or 3 any or	ne			
1	VI C after iv) co	haracterist breakdow ompare wi	ics of SCR i n, ii) Observ th datasheet	) Plot outp e the effec specificati	out V-I et of gat	character te current	istics to	o measu ward bro	re IH, IL a eak down ii	nd volta i) gate	age before and characteristics		
2	V-I ( ii) Pl speci	Characteris ot transfer fications	tics of Powe characterist	r MOSFE	T i) Plo easure ti	ot output hreshold	characte voltage	eristics iii) con	and calculanpare with	te outpi datashe	ut resistance et		
3	V-I ( trans	Characteris fer charact	tics of IGBT eristics and	i) Plot ou measure th	itput ch	aracteris d voltage	tics and iii) cor	calcula	te output re ith datashe	esistanc et speci	e ii) Plot fications		
Simul	ation	of the pov	ver converter comp	Group s mention oulsory and	B (Po) ed in g the pe	wer Con roup B u erformane	verters sing Po ce on tra	) wersim ainer kit	(PSIM) sin s.	nulation	software is		

4	Single phase Semi and Full Converter using SCR with R & R-L load i) Observe load voltage
	waveform, ii) Measurement of average o/p voltage across loads, iii) Verification of theoretical
	values with practically measured values.
5	Single-Phase PWM Power MOSFET / IGBT based bridge inverter for R and motor load i) Observe
	output voltage waveforms and measure set of rms output voltage for varying pulse width and variable
	input dc voltage for R and motor load, ii) compare measured output voltages with the
	theoretical findings
6	Step down / Step up chopper using power MOSFET / IGBT i) Measure duty cycle and observer
	effect on average load voltage for DC chopper
7	Single phase AC voltage controller using SCR for R and RL load i) Observe output rms voltage
	waveforms, ii) Measurement output voltage across load, iii) Verification of theoretical values with
	practically measured values.
	Group C (Applications of Power Electronics Converters), Any Two
	Students can use PSIM Software
8	SMPS /UPS Performance Evaluation i) find load & line regulation characteristics for no load
	condition and at 500 mA & 1A load ii) compare the performance with supplier specifications
9	To study speed control of DC / single phase AC motor
10	To design and implement a solar cell operated emergency lighting system.
Visit	to Solar power generation plant or Electric Vehicle manufacturing plant is recommended
Text	Books:
1)	M. H. Rashid, "Power Electronics Circuits Devices and Applications", PHI,4th Edition 2017
New	Delhi.
2)	M. D. Singh and K. B. Khanchandani, "Power Electronics", TMH, 2 nd Edition 2006.
Refer	rence Books:
1)	Ned Mohan, T. Undeland & W. Robbins, "Power Electronics Converters Applications and
Desig	gn, John Willey & sons, Singapore, 2 nd Edition Oxford University Press, New Delhi, 2005
2)	Muhammad H. Rashid, "Power Electronics Handbook", Academic Press, 2nd Edition, 2001.
3)	Bogdan M. Wilamowski, J. David Irwin, "The Power Electronics and Motor Drives
Hand	book", CRC Press, 1 st Edition, 2011. ; eBook: ISBN 9780429165627, 2019.
4)	SCR Manual by GE Company

<b>Program:</b>	B. Tech.	(E&TC)		Semester:	V		
Course:	Advance	d Microcont		Code:	BET5503		
Teaching Scheme   Evaluation Scheme							
Lecture	Practical	Tutorial	Credit	IE	MTE	ЕТЕ	Total
2	1		2	20	30	50	100

#### **Prior Knowledge of:**

Microcontroller is essential

#### **Course Objectives:**

- 1. To understand need and application of ARM Microprocessors in embedded system.
- 2. To study the architecture of ARM series microprocessor.
- 3. To understand architecture and features of typical ARM7 Processors.
- 4. To learn interfacing of real world input and output devices.

#### **Course Outcomes:**

1: Students will be able to describe the different ARM processors.

2: Students will be able to explain the ARM microprocessor architectures and its feature.

3: Students will be able to design and write programs for the advanced peripherals

interfaced with ARM based microcontroller

4: Students will be able to develop embedded system with available resources.

#### **Detailed Syllabus:**

Unit	Description	Duration
1.	Unit I: Introduction to ARM processors and its versions -ARM7, ARM9 & ARM11 features, advantages & suitability in embedded application ARM7 registers, CPSR, SPSR, ARM and RISC design philosophy, ARM7 data flow model, programmer's model, modes of operations	6
2.	<b>Unit II: -ARM7 Based Microcontroller LPC2148:</b> Features, Architecture (Block Diagram and Its Description), System Control Block (PLL and VPB divider), Memory Map, GPIO, Pin Connect Block, Timer, simple LPC2148 GPIO Programming examples using timers of LPC2148	6
	to generate delay	
3.	<b>Unit III: ARM Real World Interfacing Part I (6Hrs)</b> : Interrupt structure of LPC2148, Interfacing with LED, LCD, GLCD, KEYPAD, simple LPC2148 USART Programming, on-chip ADC, Waveform generation using DAC All programs in embedded C.	6
4.	<b>Unit IV: ARM Real World Interfacing Part II (6Hrs)</b> : – GSM, GPS module interfacing, Study of protocols I2C, SPI, RTC (DS1306) with I2C, and EEPROM with SPI, All programs in embedded C. Introduction to	6

ARM cortex series, CORTEX A, R, M processors, Firmware development using CMSIS Standard.	
Total	24

1. Barry Bray The Intel Microprocessors: Architecture, Programming and Interfacing 8th Edition by Pearson Education

2. Andrew Sloss ARM System Developer's Guide by ELSEVIER

#### **Reference Books:**

- 1. LPC 214x User manual (UM10139) :- www.nxp.com
- 2. ARM architecture reference manual : www.arm.com

# "Knowlege Brings Freedom"

Progress Credibility Confidence Optimism Excellence

Shoce 1999

Course : Advanced Microcontroller Lab         Code :BET5504           Teaching Scheme         Evaluation Scheme           Lecture         Pract         Tutori         Cre         T         O         PR         Tot al           1         1         25         25         50           Prior knowledge of:	Program	: B. Tech. (	(E&Tc)			V						
Teaching Scheme       Evaluation Scheme         Lecture       Pract ical       Tutori al       Cre dit       T W       O W       PR       Tot al         1       1       25       25       50         Prior knowledge of:	Course :	Advanced	Microcontr	oller Lab	b Code :BET5504							
Lecture         Pract ical         Tutori al         Cre dit         T W         Q R         PR         Tot al           1         1         25         25         50           Prior knowledge of:         .	Teaching	Scheme			Evaluation Scheme							
1       25       25       50         Prior knowledge of:       1.       Microcontroller is essential       0         Objectives:       3.       To understand architecture of typical ARM7 Processors.       4.       To learn utilization of hardware and software tools         5.       To learn interfacing of real world input and output devices.       0         Outcomes:       At the end of Laboratory work, the students will be able to:       1:         1: Students will be able to demonstrate the use of hardware and software tools.       2:         2: Students will be able to integrate peripherals and microcontroller to design an application.       3:         3: Students will be able to develop real time application.       3:         4: Interfacing stip to develop real time application.       0         5: List of Experiments       0         No.       1       LED Blinking using TIMER         2       Interfacing with 16x2 LCD       3         3       KEYPAD & LCD interfacing       4         4       Interfacing LPC2148 for serial reception and transmission from/to computer.         6       Interfacing GSM with LPC2148 for sending and receiving message and voice call.         7       Interfacing GPS with LPC2148 for finding current location latitude and longitude values.         8       Using built-in ADC of LPC2148 for displ	Lecture	Pract ical	Tutori al	Cre dit	T W	O R	PR	Tot al				
Prior knowledge of:         1. Microcontroller is essential         Objectives:         3. To understand architecture of typical ARM7 Processors.         4. To learn utilization of hardware and software tools         5. To learn interfacing of real world input and output devices.         Outcomes:         At the end of Laboratory work, the students will be able to:         1: Students will be able to demonstrate the use of hardware and software tools.         2: Students will be able to integrate peripherals and microcontroller to design an application.         3: Students will be able to develop real time application.         3: Students will be able to develop real time application.         General Guidelines: Any Eight Experiments is to be performed.         Detailed Syllabus:         Expt.       List of Experiments         No.       I         1       LED Blinking using TIMER         2       Interfacing with 16x2 LCD         3       KEYPAD & LCD interfacing         4       Interfacing LPC2148 with GLCD to display image on it.         5       Using UART of LPC2148 for senial reception and transmission from/to computer.         6       Interfacing GSM with LPC2148 for senial and receiving message and voice call.         7       Interfacing GPS with LPC2148 for finding current location latitude and longitude values.	<b></b>	1			25		25	50				
1. Microcontroller is essential         Objectives:         3. To understand architecture of typical ARM7 Processors.         4. To learn utilization of hardware and software tools         5. To learn interfacing of real world input and output devices.         Outcomes:         At the end of Laboratory work, the students will be able to:         1: Students will be able to demonstrate the use of hardware and software tools.         2: Students will be able to integrate peripherals and microcontroller to design an application.         3: Students will be able to develop real time application.         3: Students will be able to develop real time application.         General Guidelines: Any Eight Experiments is to be performed.         Detailed Syllabus:         Expt.         List of Experiments         No.         1       LED Blinking using TIMER         2       Interfacing with 16x2 LCD         3       KEYPAD & LCD interfacing         4       Interfacing LPC2148 with GLCD to display image on it.         5       Using UART of LPC2148 for senial reception and transmission from/to computer.         6       Interfacing GSM with LPC2148 for sending and receiving message and voice call.         7       Interfacing GPS with LPC2148 for finding current location latitude and longitude values.         8       Using built-in ADC of LP	Prior kno	owledge of:										
Objectives:         3. To understand architecture of typical ARM7 Processors.         4. To learn utilization of hardware and software tools         5. To learn interfacing of real world input and output devices.         Outcomes:         At the end of Laboratory work, the students will be able to:         1: Students will be able to demonstrate the use of hardware and software tools.         2: Students will be able to integrate peripherals and microcontroller to design an application.         3: Students will be able to develop real time application.         3: Students will be able to develop real time application.         Detailed Syllabus:         Detailed Syllabus:         Expt.         1       LED Blinking using TIMER         2       Interfacing with 16x2 LCD         3       KEYPAD & LCD interfacing         4       Interfacing LPC2148 with GLCD to display image on it.         5       Using UART of LPC2148 for senial reception and transmission from/to computer.         6       Interfacing GPS with LPC2148 for sending and receiving message and voice call.         7       Interfacing GPS with LPC2148 for finding current location latitude and longitude values.         8       Using built-in ADC of LPC2148 for displaying its values (Programming built-in ADC with interrupt)	1. Micro	controller i	s essential									
Outcomes:         At the end of Laboratory work, the students will be able to:         1: Students will be able to demonstrate the use of hardware and software tools.         2: Students will be able to integrate peripherals and microcontroller to design an application.         3: Students will be able to develop real time application.         3: Students will be able to develop real time application.         General Guidelines: Any Eight Experiments is to be performed.         Detailed Syllabus:         Expt.       List of Experiments         No.       Interfacing with 16x2 LCD         3       KEYPAD & LCD interfacing         4       Interfacing LPC2148 with GLCD to display image on it.         5       Using UART of LPC2148 for senial reception and transmission from/to computer.         6       Interfacing GSM with LPC2148 for senial receiving message and voice call.         7       Interfacing GPS with LPC2148 for finding current location latitude and longitude values.         8       Using built-in ADC of LPC2148 for displaying its values (Programming built-in ADC with interrupt)	<b>Objective</b> 3. To 4. To 5. To	es: understand learn utiliza learn interfa	architecture ation of hard acing of real	of typical ware and s world inp	ARM7 Proce software tools but and output	ssors. devices.	c					
General Guidelines: Any Eight Experiments is to be performed.         Detailed Syllabus:         Expt. No.       List of Experiments         1       LED Blinking using TIMER         2       Interfacing with 16x2 LCD         3       KEYPAD & LCD interfacing         4       Interfacing LPC2148 with GLCD to display image on it.         5       Using UART of LPC2148 for serial reception and transmission from/to computer.         6       Interfacing GSM with LPC2148 for sending and receiving message and voice call.         7       Interfacing GPS with LPC2148 for finding current location latitude and longitude values.         8       Using built-in ADC of LPC2148 for displaying its values (Programming built-in ADC with interrupt)	Outcome At the end 1: Stud 2: Stud 3: Stud	s: I of Labora ents will be ents will be ents will be	tory work, the able to demendent of the able to interest able to deve	ne students nonstrate th grate perip elop real ti	s will be able to be use of hard oherals and mi me applicatio	o: ware and soft crocontroller n.	ware tools. to design an a	pplication.				
No.       List of Experiments         1       LED Blinking using TIMER         2       Interfacing with 16x2 LCD         3       KEYPAD & LCD interfacing         4       Interfacing LPC2148 with GLCD to display image on it.         5       Using UART of LPC2148 for serial reception and transmission from/to computer.         6       Interfacing GSM with LPC2148 for sending and receiving message and voice call.         7       Interfacing GPS with LPC2148 for finding current location latitude and longitude values.         8       Using built-in ADC of LPC2148 for displaying its values (Programming built-in ADC with interrupt)	General	List of F	Any Eight	Experime	ailed Syllabu	s:						
1       LED Blinking using TIMER         2       Interfacing with 16x2 LCD         3       KEYPAD & LCD interfacing         4       Interfacing LPC2148 with GLCD to display image on it.         5       Using UART of LPC2148 for serial reception and transmission from/to computer.         6       Interfacing GSM with LPC2148 for sending and receiving message and voice call.         7       Interfacing GPS with LPC2148 for finding current location latitude and longitude values.         8       Using built-in ADC of LPC2148 for displaying its values (Programming built-in ADC with interrupt and without interrupt)	No.	List of E	speriments									
<ul> <li>2 Interfacing with 16x2 LCD</li> <li>3 KEYPAD &amp; LCD interfacing</li> <li>4 Interfacing LPC2148 with GLCD to display image on it.</li> <li>5 Using UART of LPC2148 for serial reception and transmission from/to computer.</li> <li>6 Interfacing GSM with LPC2148 for sending and receiving message and voice call.</li> <li>7 Interfacing GPS with LPC2148 for finding current location latitude and longitude values.</li> <li>8 Using built-in ADC of LPC2148 for displaying its values (Programming built-in ADC with interrupt and without interrupt)</li> </ul>	1	LED Blink	king using T	IMER	Wee Jean							
<ul> <li>KEYPAD &amp; LCD interfacing</li> <li>Interfacing LPC2148 with GLCD to display image on it.</li> <li>Using UART of LPC2148 for serial reception and transmission from/to computer.</li> <li>Interfacing GSM with LPC2148 for sending and receiving message and voice call.</li> <li>Interfacing GPS with LPC2148 for finding current location latitude and longitude values.</li> <li>Using built-in ADC of LPC2148 for displaying its values (Programming built-in ADC with interrupt and without interrupt)</li> </ul>	2	Interfacing	g with 16x2	LCD								
<ul> <li>Interfacing LPC2148 with GLCD to display image on it.</li> <li>Using UART of LPC2148 for serial reception and transmission from/to computer.</li> <li>Interfacing GSM with LPC2148 for sending and receiving message and voice call.</li> <li>Interfacing GPS with LPC2148 for finding current location latitude and longitude values.</li> <li>Using built-in ADC of LPC2148 for displaying its values (Programming built-in ADC with interrupt and without interrupt)</li> </ul>	3	KEYPAD	& LCD inte	rfacing								
<ul> <li>5 Using UART of LPC2148 for serial reception and transmission from/to computer.</li> <li>6 Interfacing GSM with LPC2148 for sending and receiving message and voice call.</li> <li>7 Interfacing GPS with LPC2148 for finding current location latitude and longitude values.</li> <li>8 Using built-in ADC of LPC2148 for displaying its values (Programming built-in ADC with interrupt and without interrupt)</li> </ul>	4	Interfacing	g LPC2148 v	with GLCI	D to display in	nage on it.						
<ul> <li>6 Interfacing GSM with LPC2148 for sending and receiving message and voice call.</li> <li>7 Interfacing GPS with LPC2148 for finding current location latitude and longitude values.</li> <li>8 Using built-in ADC of LPC2148 for displaying its values (Programming built-in ADC with interrupt and without interrupt)</li> </ul>	5	Using	UART of LI	PC2148 fo	r serial recept	ion and transr	nission from/t	o computer.				
<ul> <li>7 Interfacing GPS with LPC2148 for finding current location latitude and longitude values.</li> <li>8 Using built-in ADC of LPC2148 for displaying its values (Programming built-in ADC with interrupt and without interrupt)</li> </ul>	6	Interfa	cing GSM w	vith LPC2	148 for sendin	g and receivin	ng message an	d voice call.				
8 Using built-in ADC of LPC2148 for displaying its values (Programming built-in ADC with interrupt and without interrupt)	7	Interfa values	cing GPS w	ith LPC21	48 for finding	current locati	ion latitude an	d longitude				
ADC with interrupt and without interrupt)	8	Using	built-in AD	C of LPC2	148 for displa	ying its value	s (Programmi	ng built-in				
interrupt and without interrupt)		ADC v	with									
		interru	pt and witho	out interrup	pt)							

9	Waveform Generation using DAC
10	Interfacing EEPROM to LPC2148 using I2C protocol

# **Reference Books:**

- 1. Andrew Sloss ARM System Developer's Guide by ELSEVIER
- 2. LPC 214x User manual (UM10139):- <u>www.nxp.com</u>
- 3. ARM architecture reference manual : www.arm.com



Progra	am: B	V											
Course	Course:         Multidimensional Signal Simulation         Code:         I												
	T	eaching	g Scheme			Evalu	ation Schem	e					
Lectu	re Pra	actical	Tutorial	Credit	IE	MTI	E ETE	Total					
2				2	20	30	50	100					
Prior 1	Knowle	dge of:	Basic Signal	ls and Signa	al Processing is	s essent	ial						
Course	Course Objectives:												
	1 Mol	za tha a	tudanta fami	lior to diffo	rant dimansion	alsian	<b>a</b> 1a						
<ol> <li>Develop an ability to design an 2D, 3D, 4D and 5D applications.</li> </ol>													
<b>Course Outcomes:</b> The students are able to													
Course Outcomes: The students are able to													
1.	Identify	the dif	ference betw	veen differe	nt dimensional	l signal	s.						
2.	Apply 3	3D buil	der to design	an applicat	tion.								
3.	Design	an 4D a	application.										
4.	Design	<u>an 5D a</u>	application.	-bwaa	Co	11-							
Detaile	ed Sylla	bus:											
Unit	Descri	ption	18	/			2	Duration					
1.	Introdu	ction to	Dimension	n: 0D, 1D,	2D, 3D, 4D,	and 5	D. Difference	,					
	betwee	n vector	r and tensor,	Variables/p	oarameters, Re	present	ation	2					
2.	0D and	l 1D ve	ctors: Introd	luction, rep	resentation, di	fference	e between OD	1					
	and 1D	, applic	ations, Case	study: App	lication to batt	tery age	eing, Software	6					
	tool Mo	odelica	/Python/ GT	-SUITE									
							1 05						
3.	2D and	3D ve	ctors: Introd	uction, rep	resentation, di	fference	e between OD						
	1D, 21	D and	3D, applie	cations, Ca	ise study: ge	eologica	al/geophysical	8					
	explora	tion, S	oftware tool	3D builder.	, Catia /Invento	or							
4	4D and	5D ve	ctors. Introd	uction repr	resentation dif	ference	between 3D						
	4D and	5D. an	plications. C	ase study: S	Satellite/Medic	al Imag	ving	8					
	TD und	<b>5D</b> , up	phoneine, c	use study.	Jaconneo, mieare	ar mag	58						
	Total							24					
Text B	ooks:												
1	One-Di	mensio	nal Digital S	ignal Proce	ssing (Flectric	al and (	Computer End	vineering) 1st					
F. Editior	by C.	Chen			ssing (Lieethe			sincering) 1st					
2.	Two-di	mensio	nal Signal ar	nd Image Pr	ocessing by Ja	e S. Liı	n. Prentice H	all					
3.	Recent	Advand	ces of 4D Pri	nting Tech	nologies Towa	rd Soft	Tactile Senso	rs by Yuneng					
Tang1, Baiqian Dai1, Bin Su2 and Yusheng Shi2, REVIEW article													
4. Reservoir Monitoring, 4D Signal, And Fiber-Optic Technology, by Steve Maas, Rune													
Tengha	amn, Bre	ett Buni	1										
5.	https://i	ukshan	pramoditha.	medium.com	m/real-world-e	xample	<u>es-of-0d-1d-2d</u>	<u>1-3d-4d-and-</u>					
-	5d-tens	ors-100	b0837ced4			11		, , <b>,</b>					
6.	nttps://i	nedium d35fea	<u>1.com/secure</u>	-and-private	<u>e-ai-writing-ch</u>	allenge	/introduction	<u>-to-tensors-1-</u>					
7.	http://w	<u>ww.di</u> f	ferencebetw	<u>een.info/d</u> if	ference-betwe	<u>en-2d-</u> 3	d-and-4d						

- 8. https://www.academia.edu/41739709/Fifth\_Dimension\_5D\_Science
- 9. http://dusk.geo.orst.edu/gis/lec14\_3d.html
- 10. https://www.insightsonindia.com/2015/11/21/5-write-note-4-d-5-d-imaging-technologies-applications-150-words/



Progran	n: B. Tech. (E&T	<b>c</b> )			Sen	nester :	V				
Course : Multidimensional Signal Simulation LabCode : BET550											
Teaching Scheme   Evaluation Scheme											
Lectu	re Practical	Tutorial	Credit	TW	OR	PR	Total				
	2		1	25		25	50				
Prior kn	owledge of: Prog	ramming lang	guage is esse	ntial.							
Course (	Objectives:										
1. To design the specific application for 1 to 5 dimensional signal.											
Outcom	es: At the end of I	Laboratory wo	ork, the stude	ents will be	able to:						
1. D	esign an applicati	on using 3D	builder.								
2. D	esign an 4D appli	cation.									
3. D	esign an 5D appli	cation									
General conducto	Guidelines: Any ed on Modelica /I	Eight Exper Python/ GT-	<sup>.</sup> imen <mark>ts</mark> is to SUITE.	be perforn	ned. Exp	eriment	s will be				
Detailed	Syllabus:					60					
Expt. No.	List of Experim	ients	Bulace	UE	2011						
1.	Study of 1 D and	l 2 D Library	je brings	Freedor	0						
2.	Design and Impl	ementation o	f the battery	ageing	1						
3.	Verification of the	ne battery age	eing								
4.	Study of 3D Lib	rary from 3D	builder/ Cati	ia/Inventor							
5.	Design and Impl builder	ementation o	f geological/	geophysical	explorat	tion usin	g 3D				
6.	Verification of g	eological/geo	physical exp	oloration usi	ng 3D bi	uilder					
7.	Study of 4D Lib	rary from 4D	Satellite/Me	dical Imagi	ng Appli	cation.					
8.	Design and Impl	ementation o	f 4D Satellite	e/Medical II	naging A	pplication	on.				
9.	Verification of 4	D Satellite/M	Iedical Imagi	ng Applica	tion.						
10.	Design and Impl	ementation of	of 5D electro	nics/electric	al based	Applica	tion				
11.	Verification of 3	5D electronic	s/electrical b	ased Applic	ation						

- 1. One-Dimensional Digital Signal Processing (Electrical and Computer Engineering) 1st Edition by <u>C. Chen</u>
- 2. Two-dimensional Signal and Image Processing by <u>Jae S. Lim</u>, Prentice Hall
- 3. Recent Advances of 4D Printing Technologies Toward Soft Tactile Sensors by <u>Yuneng Tang</u>, <u>Baiqian Dai</u>1, <u>Bin Su</u> and <u>Yusheng Shi</u>, REVIEW article
- 4. Reservoir Monitoring, 4D Signal, And Fiber-Optic Technology, by <u>Steve Maas</u>, <u>Rune Tenghamn</u>, <u>Brett Bunn</u>
- 5. <u>https://rukshanpramoditha.medium.com/real-world-examples-of-0d-1d-2d-3d-4d-and-5d-tensors-100b0837ced4</u>
- 6. <u>https://medium.com/secure-and-private-ai-writing-challenge/introduction-to-tensors-1-de7dded35fea</u>
- 7. <u>http://www.differencebetween.info/difference-between-2d-3d-and-4d</u>
- 8. <u>https://www.academia.edu/41739709/Fifth\_Dimension\_5D\_Science</u>
- 9. http://dusk.geo.orst.edu/gis/lec14\_3d.html
- 10. <u>https://www.insightsonindia.com/2015/11/21/5-write-note-4-d-5-d-imaging-technologies-applications-150-words/</u>

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Progress Credibility Confidence Optimism Excellence

Shace 1999

Program: B. Tech. (E&TC) Semester:							V	
Course:         Information Theory and Coding					(	Code:	BET5507	
	Teaching	g Scheme			Evalua	tion Scheme		
Lecture	Practical	Tutorial	Credit	IE	MTE	ЕТЕ	Total	
2			2	20	30	50	100	
<b>Prior Kn</b> <b>2.</b> B	owledge of:	s of Probabil	ity and con	nmunication sy	stem is e	ssential		
Course C	bjectives:							
1. 2. 3. 4	<ol> <li>To introduce the terminology and basic concepts of information theory.</li> <li>To encourage the students to study the different data compression methods.</li> <li>To motivate the students to study the different error coding techniques</li> </ol>							
т.			illillar witti	different types		concerning et	Jues	
Course O	utcomes:						00	
Student w	vill be able						-	
1 2 3 4	<ul> <li>To apply th</li> <li>To analyze</li> <li>To constru-</li> <li>To identify</li> </ul>	ne basics con the differen ct the differen the differen	cept of info t data comp ent error coo t types of e	ormation theory ression methor ling techniques rror correcting	y. d <mark>s.reed</mark> s codes	om" ce	× .	
Detailed	Syllabus:		C Op	fimism Excel	ence			
Unit D	escription			Since 199			Duration	
1. In in pr	troduction formation, E operties, Dis	to Informa ntropy and i crete memor	tion theor nformation y less chan	y:- Probability rate, mutual i nel, Channel ca	y, Uncer nformati apacity	tainty, self- on and their	6	
2. So cc cr	Source Coding:-Source coding theorem, Data compression, Huffman           coding, Lempel-Ziv coding, Run-length encoding, Introduction to           cryptography           5							
R	eview on reco	ent Research	Papers					
3. C.	Channel Coding:- Channel coding theorem, Introduction to Error control codes, Block codes, linear block codes, cyclic codes, BCH and RS codes       7         Review on recent Research Paper       7							
	<b>T</b> /•	<u> </u>	1		<u> </u>			
4. Co	onvolution en onvolution en ode, LDPC co	Code :- Int acoder and I ade, ARQ	roduction f Decoder, Tu	o Convolution irbo codes, Re	n Codes, petition	Properties, code, Golay	6	

	Total	24
I		
Text B	ooks:	
3. 4.	Simon Haykin, "Communication Systems", 4th Edition, John Wiley and Sc Ranjan Bose, —Information Theory coding and Cryptographyl, McGraw-H 4th Edition	ons, 2001. Iill, 2nd E,
Refere	nce Books:	
	<ol> <li>Shu lin and Daniel j, Cistello jr., —Error control Coding Pearson, 2nd 5. Todd Moon, —Error Correction Coding : Mathematical Methods and A Wiley, ISBN: 978-0-471-64800-0,2nd Edition</li> <li>Khalid Sayood, —Introduction to Data compression Morgan Kaufman 2nd Edition</li> </ol>	Edition. Algorithms  , nn Publishers,
NPTE	L/ MOOC courses	
1. An 1	introduction to Information Theory	
https:/	/onlinecourses.nptel.ac.in/noc22_ee49/preview	
<b>.</b>		
2. Info	rmation Theory //onlinecourses.nptel.ac.in/noc20_ee96/preview	$\lambda$
	E AA	reing
	"Knowlege Brings Freedom"	

Γ

Program: B. Tech. (E&Tc)Semester :V						:V			
Course : 1	TCT Lab				Code :BE	CT5508			
Teaching S	cheme			Evaluation S	Scheme				
Lecture	Practica l	ctica Tutoria Credi		TW	O R	PR	Tot al		
	2		1	25	-	25	50		
<ol> <li>Prior know</li> <li>Basic co</li> <li>MATL</li> </ol>	v <b>ledge of:</b> oncepts of Pro AB /Simulink	bability and o / Open source	communicati e platform is	on system essential					
Objectives	•								
2. T 3. T Outcomes: At the end of 1. T 2. D 3. D co General G	o inculcate the o instill the kr of Laboratory o analyze the oesign and veri perior and veri prection.	e implementa nowledge of v work, the stu different term ify the source ify the Chann y Eight Expe	tion of source various chann dents will be ninologies re coding algo nel coding algo rel coding algo	e coding techni ael coding techni able to: lated to informa rithm for data c gorithm for erro	eques for data niques and the ation theory compression or detection an d.	compression eir implement	tation.		
		200	Detaile	d Syllabus:		3			
Expt. No.	List of Expe	riments	7			3			
1	Write a prog	ram to find th	ne entropy fo	r the given sou	rce	9			
2	Write a prog given channe	ram to find d el	ifferent entro	pies, Mutual in	nformation ar	nd channel ca	pacity for		
3	Write a prog	ram to find th	ne coding eff	iciency using H	Iuffman sourc	e coding			
4	Write a prog	gram to encoc	le and decod	e using LBC	hidence				
5	Write a prog	ram to encod	e and decode	e using Cyclic c	code				
6	Write a prog	ram to encod	e and decode	e using BCH co	de				
7	Write a prog	ram encode a	and decode u	sing RS code					
8	Write a prog	ram encode a	and decode u	sing Convolutio	on code				
9	Case study o	n Data comp	ression						
10	To study the	applications	of different t	ypes of code					
11	To study the	Cryptograph	ny techniques	5					

#### **Reference Books:**

- 1. Ranjan Bose, —Information Theory coding and Cryptographyl, McGraw-Hill, 2nd Ed
- Murlidhar Kulkarni, K.S.Shivaprakasha, —Information Theory & Coding, Wiley Public 2.
- Simon Haykin, —Communication Systems, John Wiley & Sons, Fourth Edition. 3.
- 4.
- Shu lin and Daniel j, Cistello jr., —Error control Coding Pearson, 2nd Edition. Todd Moon, —Error Correction Coding : Mathematical Methods and Algorithms , Wiley Publication 5.
- Khalid Sayood, —Introduction to Data compression, Morgan Kaufmann Publishers 6.



<b>Program:</b>	B. Teo	<b>B. Tech. (E&amp;TC)</b>						Semester: V			
Course:	Object Oriented Programming					Co	ode:	BET5509			
	Т	eaching Sche	eme	I		Evaluation Scheme					
Lecture	Practi cal	Tutorial	Credit	Hours	IE		MTE	ETE	Total		
2			2	2	20		30	50	100		
Prior Knowledge of:											
1D	1Data Structures										
2.0	program	nming									
	• .•										
Course Ot	ojectives	:									
1. Ma	ke the	students fan	niliar with	i b <mark>asic cor</mark>	icepts	anc	l technique	es of obje	ct oriented		
2 Dev	grammin velop an	lg ability to write	te program	$\sin C \cup for$	r proble	m	olving				
2. Dev 3. Ma	ke the sti	udents famili	ar with mo	dern C++	proble	5111 3	sorving.				
Course Ou	itcomes:	On complet	tion of the	course, learn	ner will	be	able to -				
		1.5	/								
CO1: Desc	ribe the j	principles of	object orie	nted program	nming.						
CO2: Appl	y the cor	icepts of clas	ses and me	thods to wr	ite prog	gran	ns in C++.	C			
CO3: Appl	y the cor	icepts of inne	eritance and	a polymorph	iism to	wr	ite program	s C++.			
CO4: Write	e the prop	grams in C++	-11 and C+	-+14.							
D ( 1 10			TO THE		4						
Detailed S	ynabus:										
		"K	nowlea	e Brinas	Free	do	m"		Dur		
Unit	Descrip	otion		i i i g -					atio		
									n		
1	Fundar	nental of Oh	ject Orier	ted Progra	mmino	r					
1.	Introduc	ction to ob	ject-orient	ed program	nming.	s L	imitations	of proced	lural		
	program	nming, Funda	amentals o	f object-orie	ented p	rog	ramming: c	bjects, cla	sses,		
	data me	embers, meth	nods, mess	sages, data	encaps	ula	tion, data a	abstraction	and 6		
	informa	tion hiding,	inheritan	ce, polymo	orphism	ı. 1	Inline func	tion, Fund	ction		
	overloa	ding. Dynami	ic initializa	tion of varia	bles, m	em	ory manage	ment opera	tors,		
	Membe	r dereferencii	ng operator	rs, operator j	precede	ence	e, typecast o	perators, S	cope		
2	resolutio	on operators.									
2.	Classes	a Objects:									
	Definin	g class, Defir	ning memb	per functions	, static	dat	ta members	, static mer	nber		
	function	ns, private da	ata membe	ers, public n	nember	· fu	nctions, arr	ays of obj	ects, 6		
	objects	as function a	rguments.								
	Constru	ctors and D	Destructors	types of	constru	ucto	ors, handlir	ng of mul	tiple		
	construe	ctors, destruc	tors.								
3.	Operat	or Overload	ing								
	Fundam	entals of Op	erator Ove	rloading, Re	estrictio	ons	on Operator	rs Overload	ling,		
	Friend I	Functions, Ov	verloading	Unary Oper	ators, C	Ove	rloading Bi	nary Opera	tors, 6		
	Overloa	ding of operation	ators using	friend funct	ions.		-	_			
	Inherit	ance & Poly	morphism								

	Introduction to inheritance, base and derived classes, types of inheritance, hybrid inheritance, member access control, static class, multiple inheritance, ambiguity, virtual base class, Introduction to polymorphism, virtual functions, pure virtual functions, abstract base class, Polymorphic class, virtual destructors, early and late binding.	
4.	Introduction to C++11 and C++14 Summary of the standard C and C++ libraries, Container classes, Container adapters, Creating and accessing containers, Initializer lists, Common Container Methods, Custom allocators, std::array, Lambda Functions, Filling a container, Non-modifying operations.	6
	Total	24
<ol> <li>E Bala</li> <li>Herber</li> <li>Scott I</li> <li>Reference</li> <li>Rober</li> <li>Parasce</li> <li>Yashw</li> <li>Paul L</li> </ol>	gurusamy, "Programming with C++", Tata McGraw Hill, 3rd Edition. tt Schildt, "The Complete Reference C++", 4th Edition. Meyers, "Effective Modern C++ (2014)" <b>Ce Books:</b> "Knowlege Brings Freedom" Cafore, "Object Oriented Programming in C++", Sams Publishing, 4th Edition. ns, "Object Oriented Programming with C++", BPB Publication, 1999. Part Kanethkar, "Object Oriented Programming using C++", BPB, 2004 aurence, "Effective Modern C++ - C++ 11, - C++ 14".	
MOOC / 1. NPTE https://np 2. Udem https://w	<pre>/ NPTEL Courses: L Course "Programming in C++" otel.ac.in/courses/106/105/106105151/ y course "Complete Modern C++ (C++11/14/17)" ww.classcentral.com/course/udemy-beg-modern-cpp-23507</pre>	

Program: H	B. Tech. (E&T	Гc)	Semester :V						
Course : O	bject Oriente	d Programn	Code : BET5510						
Teaching S	cheme			<b>Evaluation Sc</b>	on Scheme				
Lecture	Practica l	Tutoria l	Credi t	TW	OR	PR	Tota l		
	2		1	25		25	50		
Prior know 1. Dat 2. C p	ledge of: ta Structures programming								
Course Obje Faculty nee 2. Devel 3. Devel	ectives: d to : op an ability t	to write prog	rams in C++	by applying obje 11 and C++14.	ect oriented pro	ogramming co	ncepts.		
Outcomes: CO1: Apply to CO2: Apply to CO3: Write to General Gu to be perfor	At the end of the concepts o the concepts o <u>he programs i</u> <b>nidelines: Any</b> <b>rmed.</b>	Laboratory v of classes and of inheritance <u>n C++11 and</u> y <b>Five Exper</b>	ork, the stud methods to v and polymon C++14. iments from	lents will be able write programs in phism to write p a <b>group A and A</b>	e to: n C++. programs C++.	periments from	m group B are		
Expt. No.	List of Expe	eriments							
Group A:									
1.	Write a progr sort and swap	ram in C++ to o	sort the nun	bers in an array	using separate	e functions for	read, display,		
2.	Write a C++ ]	program that	illustrates the	e concept of Fun	ction over load	ding.			
3.	Write a progr Multiply, Div	am in C++ to vide, Complex	perform foll conjugate.	lowing operation	is on complex	numbers Add,	Subtract,		
4.	Write a progr performed on	am in C++ to stack. Use C	o implement s constructors a	Stack. Design the and destructors.	e class for stac	k and the oper	ations to be		
5.	Write a progr Multiply, Div	am in C++ to vide. Use ope	perform foll rator overloa	lowing operation ding for these op	s on complex perations.	numbers Add,	Subtract,		
6.	Write a progr Inheritance. U	am in C++ to Jse Basic Inf	Read and D and Depart	isplay the inforn ment Info as a ba	nation of Emplase classes of l	loyee Using M Employee class	ultiple s.		
7.	Write a C++ j	program that	illustrates ru	n time polymorp	hism by using	virtual functio	ons.		
Group B:									
8.	Write a C++	11 program f	or Lamba Ex	pressions of Lan	nbda Function	S.			
9.	Write a C++	14 program f	or Lamba Ex	pressions of Lan	nbda Function	s.			
10.	Write a C++	11 program f	or Uniform I	nitialization.					

11. Write a C++ 14 program for Uniform Initialization.
Text Books:
<ol> <li>E Balagurusamy, "Programming with C++", Tata McGraw Hill, 3rd Edition.</li> <li>Herbert Schildt, "The Complete Reference C++", 4th Edition.</li> </ol>
<b>3</b> . Scott Meyers, "Effective Modern C++ (2014)".
Reference Books:
<ol> <li>Robert Lafore, "Object Oriented Programming in C++", Sams Publishing, 4th Edition.</li> <li>Parasons, "Object Oriented Programming with C++", BPB Publication, 1999.</li> </ol>
3. Yashwant Kanethkar, "Object Oriented Programming using C++", BPB, 2004
4. Paul Laurence, "Effective Modern C++ - C++ 11, - C++ 14".
MOOC / NPTEL Courses: 1. NPTEL Course "Programming in C++" https://nptel.ac.in/courses/106/105/106105151/
2. Udemy course "Complete Modern C++ (C++11/14/17)" https://www.classcentral.com/course/udemy-beg-modern-cpp-23507
FGGUE
"Knowlege Brings Freedom"

# **Program Elective-II**

Program:	B. Tech.	(E&TC)			Semester: V				
Course:	<b>Robotics and Automation (Program Elective-II)</b>					Code: BET5511			
Teaching Scheme					Evaluation Scheme				
				CIE					
Lecture	Practical	Tutorial	Credit	IE	MT F	ETE	Total		
2	_	-	2	20	30	50	100		

#### Prior knowledge of:

Basic engineering mathematics, Differential equations and Integration, Basic coordinate system,

#### **Objectives:**

#### The objectives of this course are:

1. To familiarize the students with the significance of robotic systems in agile and automated manufacturing processes.

2. To prepare the students to be conversant with robotic elements/ peripherals, their selection, and interface with manufacturing equipment's.

3. TO analyze and classify the different types of end effectors and actuators for different types of robot applications

4. To learn the fundamentals of kinematics and programming methods of robotics

#### **Outcomes:**

After learning the course, the students should be able to:

- 1. Understand the basic classification of robots with specification
- 2. Apply the knowledge of robot drivers and vision systems to understand the design of the robot
- 3. Compare & select appropriate grippers, actuators, and driving motors for particular robotics applications
- 4. Apply programming logic to develop an industrial robotic system.

**Detailed Syllabus:** 

Unit	Description	Duration (Hrs.)
Ι	<b>Basic concepts in robotics Definition;</b> anatomy of the robot, the basic structure of robot, Specifications and Classification of the robot, Safety Measures in robotics, Industrial Applications of Robots	6
II	Robot drivers, Sensors and Vision Drives for robots: Electric, hydraulic and pneumatic. Sensors: Internal-External, Contact-noncontact, position, velocity, force, torque, proximity and range. Vision: Introduction to techniques, Image acquisition and processing. Introduction of Machine Vision in Robotics, Low level & High-level Vision, Sensing & Digitizing, Image Processing & analysis, Segmentation, Edge detection, Machine vision algorithms, Applications.	6

III F	End Effectors and Actuators:	
	Different types of grippers- Mechanical, Magnetics, vacuum, Adhesive, Gripper force Analysis & Gripper Design, an overview of actuators, Power and torque, Acceleration and velocity Specifications and characteristics of Stepper motors, AC motors, DC motors and servomotors.	6
IV F	Robot Kinematics and Programming Methods Basic fundamentals of direct and inverse kinematics for industrial robots for position and prientation, Redundancy, and Manipulators. Robot language classification, Robot language tructure, elements and its functions. Simple programs on Sensing distance and direction., Line Following Algorithms.	6
	Total Hrs.	24
Text Bo	oks:	
• Ii	ntroduction to Robotics By S.K.Saha, Tata McGraw Hill	
● R H	Robotics Control, Sensing, Vision and Intelligence by K.S. Fu, R.C. Gonzalez, C.S.G.Lee , Tata M Hill	cGraw
• F	Frank D. Petruzella, "Programmable Logic Controllers", 5th Edition, McGraw- Hill, New York, 20	)16.
Referen	ce Books: Promote Control to Control on Control of Cont	
. J . R . R	. Hirchhorn: Kinematics and Dynamics of Machinery, McGraw Hill book co. Robert J. Schilling , Fundamentals of Robotics- Analysis and Control, Prentics Hall india. Robotics Technology and Flexible Automation by S.R.Deb, S. Deb, Tata McGraw Hill.	
. R	Robot Motion and Control (Recent Developments) by M.Thomas & M. Morari	

#### **NPTEL Video:**

- 1. Robotics (IIT Kharagpur) : <u>https://nptel.ac.in/courses/112105249</u>
- 2. Robotics Automation (IIT Bombay): <u>https://nptel.ac.in/courses/112101098</u>
- 3. Introduction to robotics (IIT Madras): <u>https://nptel.ac.in/courses/107106090</u>

Program: B. Tech. (E&Tc)	Semester: V
Course: Robotics and Automation Lab	Code: BET5512
(Program Elective II Lab)	

<b>Teaching S</b>	cheme			Evaluation Scheme					
Lecture	Practica l	Tutoria l	Credi t	TW	OR	PR	Tota l		
	2		1	25	25		50		
Prior know	ledge of Sens	ors, Contro	l Systems ar	nd basic progra	mming is essent	ial			
Objectives									
The main of	biective of this	s course is to							
6. To le	arn and unders	stand the bas	ics of fundar	nentals of robot	ics systems.				
7. To be	e acquainted w	ith a differen	nt configuration	ion of the roboti	cs system				
8. To de	esign MATLA	B program f	or robotic co	nfiguration					
<b>Jutcomes:</b>									
At the end of	of Laboratory	work, the stu	idents will be	e able to:					
4. Ident	ify and unders	tand the unit	lue character	istics and comp	onents of robotic	s systems			
5. Com	pare and under	rstand variou	s types of ro	botics systems		D			
$\begin{array}{ccc} 0 & \mathbf{Desig} \\ 7 & \mathbf{Com} \end{array}$	gn, simulate ar	a test kinem	atic equation	is for robotic system	of robotion system	AB			
7. Com	pare and under	rstand the va	nous mausur	iai applications	of robotics system	IIS			
General Gui	idelines: Any	Six Experim	nents is to b	e performed.					
			Deta	ailed Syllabus:					
Exp. No.	List of Expe	riments	hwar	01/0					
1	Study and an	alysis of rob	ot gripp <mark>ers (</mark>	includes the pro	blems based on g	ripper force)			
2	Demonstratio	on of various	robotic con	figurations using	g an industrial rol	bot			
3	MATLAB pi	rogram for si	mple kinema	atics of simple r	obot configuratio	n			
4	MATLAB pr	rogram for in	werse kinem	atics of simple 1	obot configuration	on			
5	To demonstra	ate a simple	robotic syste	m using Matlab	/ MscAdam / Rol	boAnalyser sof	tware		
6	Study of the	configuration	n of robots a	nd motion of rol	oot manipulator				
7	Study of pick	c and place in	ndustrial rob	ot					
8	One Industri	al visit for In	dustrial robo	tic application	om"				
0	One Industrial visit for Industrial robotic application								

• Introduction to Robotics By S.K.Saha, Tata McGraw Hill

• Robotics Control, Sensing, Vision and Intelligence by K.S. Fu, R.C. Gonzalez, C.S.G.Lee, Tata McGraw Hill

Frank D. Petruzella, "Programmable Logic Controllers", 5th Edition, McGraw-Hill, New York, 2016. **Reference Books:** 

- J. Hirchhorn: Kinematics and Dynamics of Machinery, McGraw Hill book co.
- Robert J. Schilling, Fundamentals of Robotics- Analysis and Control, Prentics Hall india.
- Robotics Technology and Flexible Automation by S.R.Deb, S. Deb, Tata McGraw Hill.

Robot Motion and Control (Recent Developments) by M.Thomas & M. Morari

#### Virtual Lab Links

- 1. Mechanisms & Robotics Lab http://vlabs.iitkgp.ernet.in/mr/
- 2. Robotics Application Lab <u>https://vlab.amrita.edu/?sub=3&brch=271&sim=1642&cnt=3525</u> 3. Bio Inspired Robotics Virtual Lab
- https://vlab.amrita.edu/?sub=3&brch=257



Program	ogram: B. Tech. (E&TC)					Semester:	V		
Course:	Digital I	Design with	VERILOG	HDL		Code:	BET5513		
	Teaching	g Scheme			Evalua	tion Scheme	2		
Lecture	Practical	Tutorial	Credit	IE	MTE	ETE	Total		
2			2	20	30	50	100		
Prior Kı	owledge of:								
<b>3.</b> I	3. Digital Logic Design Is essential								
Course (	Objectives:								
1 т	- 1 (1		1.1	1:					
I. I	o learn the c	oncepts of n	nodeling a d	digital system	using v	ernog nardw	are description		
	e e e e e e e e e e e e e e e e e e e	·/1 1°CC		Co	17 11				
2. 1	o familiarize	with differen	nt levels of	abstraction in	Verilog.				
3. L	nderstand co	ncepts of log	gic synthesis	s and basics of	verificat	10n.			
Course	Outcomes:	120	/		13	31			
	/								
After stu	lying this cou	urse, student	s will be ab	le to:					
	IE					0 0 1			
1. U	nderstand ev	olution of C.	AD and HD	L environmen	t and Ve	rilog basics.			
2. V	rite Verilog	codes using	date level a	nd Dataflow m	nodelling	•			
3. V	rite Verilog	codes using	Behavioura	l modelling.					
4. D	evelop a test	bench mode	l for design	under test.					
<b>D</b> / <b>U</b> ]	<u>a n 1</u>	"Kr	owlege	Brings Fre	edom	11			
Detailed	Syllabus:								
Unit ]	Description		Optimis	an Excellence			Duration		
1. <b>I</b>	ntroduction:	Evolution	of Cad an	d HDL envi	ronment	. Verilog as			
H	DL. Levels	of Design	Descriptio	on, Concurren	cy. Sim	ulation and			
S	vnthesis.	0	I.	, , , , , , , , , , , , , , , , , , , ,	,				
							4		
E	asics concep	ots: Lexical	convention	ns, Datatypes,	system	s tasks and			
c	ompiler direc	tives. Modu	le definitio	n, Port declara	ation and	d connecting			
p	orts, hierarch	ical referenc	ing						
2 (	oto Lovol I	Modeling	Modalling	of basic Vori	log goto	nrimitivoo			
2. 0	fale Level 1	viouening: 1	viouening	ond turn off of	log gate	in mor and			
u t	description of various gates, rise, fail and turn off delays, min, max and								
U.	typical delays. 7								
Γ	<b>Data flow modelling:</b> continuous assignments, delay specifications								
e	pressions, of	perator and o	operands.	C ,					
	• / · ]		•						
3. <b>E</b>	ehavioral N	Modeling:	Introduction	n, Operations	and A	Assignments,			
F	unctional Bit	furcation, In	itial Constr	ruct, Always	Construc	t, Design at	7		
E	ehavioral Le	vel, Blockin	g and Non-	-Blocking Ass	ignments	s, The 'Case'			
S	tatement, 'If'	and 'if-Else	e' Construct	s, 'Assign- De	e-Assign	' Constructs,			

	'Repeat' Construct, for loop, 'The Disable' Construct, 'While Loop', Forever Loop, sequential and Parallel Blocks.	
4.	<b>Test bench:</b> Test bench for sequential and combinational circuits, Test pattern generation, test bench with initial block. Introduction to score boards, verification model and verification environment.	6
	Total	24

- 5. T.R. Padmanabhan and B. Bala Tripura Sundari, "Design through Verilog HDL", WSE, IEEE Press 2008.
- 6. 2. J. Bhaskar, "A Verilog Primer", BSP, 2nd edition 2003.

#### **Reference Books:**

1. Samir Palnitkar, "Verilog HDL", Pearson Education, 2nd Edition, 2003.

2. Thomas and Moorby, "The Verilog Hardware Description Language", kluwer academic publishers, 5th edition, 2002

3. Stephen Brown and Zvonko Vranesic, "Fundamentals of Logic Design with Verilog", TMH publications, 2007.

4. Charles.H.Roth,Jr., Lizy Kurian John "Digital System Design using VHDL", Thomson, 2nd Edition, 2008

"Knowlege Brings Freedom"

Intimism Excellence

Since voef

Program: B. Tech. (E&Tc)					Semester : V		
Course : Digital Design with VERILOG HDL -Lab					Code: BET5514		
Teaching So	cheme			<b>Evaluation Sc</b>	heme		
Lecture	Practical	Tutorial	Credit	ТW	OR	PR	Total
	2		1	25			25
Prior know is essential	ledge of:						
<b>Objectives:</b>							
<ul> <li>Designing digital circuits, behaviour and RTL modeling of digital circuits usin verilog HDL, verifying these Models and synthesizing RTL models to FPGAs.</li> <li>Students ain practical experience by designing, modeling, implementing and verfying several digital circuits.</li> </ul>							
Outcomes:	fIaboratory	work the stu	danta will be	able to:			
At the end of	I Laboratory	work, the stu	dents will be	able to:			
<ol> <li>Demo</li> <li>Design</li> <li>Design</li> <li>Design</li> <li>Able t</li> <li>output.</li> </ol>	<ol> <li>Demonstrate the function of adder/subtractor circuits using Verilog.</li> <li>Design and analyse the Multiplexers Decoders, Encoders circuits using Verilog.</li> <li>Design and analysis of different Flip-flops and counters using Verilog.</li> <li>Able to use FPGA/CPLD kits for down loading Verilog codes for shift registers and counters and check output.</li> </ol>						
General Gui	delines: First	t 4 assignmen	nts are compu	l <mark>lso</mark> ry and any tw	o assignment	from 4,5,6 can	be chosen by
students.							
	12		Deta	ailed Syllabus:			
Expt. No.	List of Exp	eriments	216	HO:			
1	A. Design a	and implement	nt Adder – Fu	ull/half using Ver	ilog in dataflo	w Modelling	
	B. Write a t	test bench for	4-bit ALU a	and Implement or	1 PLD		
2	A. Design a modellin	and implement	nt 4:1 Multij	plexer and 1:8 De	emux using ve	erilog in behavi	ioural
	B. Write a t	test bench for	4:1 Multiple	exer and 1:8 Dem	ux and Imple	ment on PLD	
3	A. Design a modellin	and implement	nt DFF (act	ive low-asynchro	onous reset) us	sing verilog in	behavioural
	B. Write a t	test bench for	D FF and In	nplement on PLE	)		
4	A. Design a	and implement	nt 4 bit Up-I	Down counter usi	ing verilog in	behavioural mo	odelling.
	B. Write a t	test bench for	r 4 bit Up-Do	wn counter and I	implement on	PLD	
5	A. Write bits.	e Verilog Des	cription for s	equence detector	FSM to dete	ct alternate 1's	and 0's till 4
	B. Write	a test bench	for 4 bit Up-	Down counter ar	nd Implement	on PLD	
6	A. Write	Verilog Des	cription for 4	bit Universal S	Shift Register		

B. Write a test bench for 4 bit Universal Shift Register and Implement on PLD	
A. Write Verilog Description for Random Number Generator using linear feedbregister.	oack shift
B. Write a test bench for Random Number Generator using linear feedback shif and Implement on PLD	t register.
Total Hrs	24

Reference Books:

- 1. Fundamentals of Digital Logic with Verilog Design Stephen Brown, Zvonkoc Vranesic, TMH, 2nd Edition.
- 2. Advanced Digital Logic Design using Verilog, State Machines & Synthesis for FPGA Sunggu Lee, Cengage Learning, 2012.
- 3. Verilog HDL Samir Palnitkar, 2nd Edition, Pearson Education, 2009.
- 4. Advanced Digital Design with Verilog HDL Michel D. Ciletti, PHI,2009



Progra	am: B. Tech.	m: B. Tech. (E&TC)				Semester:	V	
Cours	e: Digital I	mage Process	sing			Code:	BET5515	
	Teaching Scheme				]	Evaluation So	cheme	
Lectu	re Practical	Tutorial	Credit	IE	MTI	E ETE	Total	
2			2	20	30	50	100	
<b>Prior</b>	Knowledge of:	Basic Signal	s and Signa	al Processing is	s essent	ial		
Cours	Course Objectives:							
1.	Understand the	e fundamenta	l concepts	of Digital Imag	e Proc	essing with ba	sic relationship of pixels	
	and mathemati	cal operation	ns on 2-D d	ata.	5		F F	
2.	Learn design a	nd integrate	image enha	nc <mark>e</mark> ment.				
3.	Learn the need	for effective	use of reso	ources such as	storage	and bandwidt	h and ways to provide	
	effective use o	f them by da	ta compress	si <mark>on tech</mark> niques	, °°0,			
4.	Understand ob	ject segment	ation and ir	nage analysis t	echniqu	les		
Cours	e Outcomes: T	he students a	re able to	-	1	32.		
On cor	npletion of the	course, stude	nt will be a	ble to				
	inpretion of the	, stude						
1.	Develop and in	nplement ba	sic mathem	atical operation	ns on di	gital images.		
2.	Analyze and so	olve image e	nhancemen	t problems.				
3.	Apply 2-D data	a compressio	n technique	es for digital in	nages.			
4.	4. Design & Develop image processing Algorithms for object segmentation							
Detail	Detailed Syllabus:							
Unit	Description				2		Duration	
1.	Fundamental	s of Image H	Processing:	Steps in Imag	e proce	ssing, Human		
	visual system,	Sampling	& quantiza	tion, Represer	nting d	igital images,		
	spatial and gra	ay level reso	lution, Ima	ge file formats	s, Basic	relationships	5	

 addition, subtraction, logical operations, scaling translation, rotation.

 2.
 Image Enhancement Point:Log transformation, Power law transformation, Piecewise linear transformation, Image histogram, histogram equalization, Mask processing of images, filtering operations-Image smoothing, image sharpening, frequency domains image

between pixels, Distance Measures, Basic operations on images - image

	enhancement: 2D DFT, smoothing and sharpening in frequency domain, Pseudo coloring.					
3.	<b>Image Compression</b> : Types of redundancy, Fidelity criteria, Compression models - Information theoretic perspective – Fundamental coding theorem, Lossless Compression: Huffman Coding- Arithmetic coding. Introduction to DCT, Lossy compression: DCT based compression; Wavelet based compression	5				
4.	<b>Image Segmentation</b> : Pixel classification, Bi-level thresholding, Multi- level thresholding, Adaptive thresholding, Otsu's method, Edge detection – First order derivative Prewitt and Sobel, Second order derivative – LoG, DoG, Canny. Edge linking, Hough transform, Region growing and region merging. Morphological operators: Dilation, Erosion, Opening, Closing, Hit or Miss transforms Boundary detection,	7				
	Total	24				
Text I           1. Gor           2. Iain           3. Vid           3rd Ed	<ul> <li>Text Books:</li> <li>1. Gonzalez and Woods, "Digital Image Processing", Pearson Education, 3rd edition</li> <li>2. Iain E. G. Richardson, —H.264 and MPEG</li> <li>3. Video Compression: Video Coding for Next Generation Multimedial, John Wiley and Son's Publication, 3rd Edition.</li> </ul>					
Refer	ence Books:					
1. A. K. Jain, Fundamentals of digital image processing, Prentice Hall of India, 1989.						
2. Prat	tt William K. "Digital Image Processing", John Wiley & sons					
3. A. I	Bovik, Handbook of Image & Video Processing, Academic Press, 2000					

Program: B. Tech. (E&Tc)							Semester :V		
Course	: Dig	ital Image P	rocessing La	b		Co	de : BET	5516	
Teachi	ng Scl	heme			Evaluation	Schem	e		
Lectu	ure	Practical	Tutorial	Credit	TW	OR	PR	Total	
		2		1	25	25		50	
Prior k	nowle	edge of: Prog	ramming lang	guage is esse	ential.				
Course	Obje	ctives:							
1.	Under pixels	stand the fun and mathema	damental con atical operation	cepts of Digi ons on 2-D da	ital Image p ata.	rocessin	g with ba	asic relationship of	
2.	Learn	design and ir	ntegrate imag	e enhanceme	nt.				
3.	Learn effect	the need for our of the	effective use m by data con	of resources	such as stor chniques	age and	bandwid	th and ways to provide	
4.	Under	stand object	segmentation	and image a	nalysis tech	niques			
Outcon	nes:		inch	and a man	09				
On com	pletio	on of the cours	se, student wi	ll be able to					
1.	Devel	op and imple	ment basic m	athem <mark>atic</mark> al c	operations o	n digital	images.		
2.	Analy	ze and solve	image enhand	ement proble	ems.				
3.	Apply	2-D data cor	npression tec	hniques for d	ligital image	es.			
4.	Desig	n & Develop	image proces	sing Algorith	nms for obje	ect segm	entation		
Genera	l Gui	delines: Any	Eight Exper	iments is to	be perform	ned.			
Detaile	d Svll	abus:	"Knowle	ge Brings	; Freedo	m"			
	-		Progress	Credibility	Confidence	2 /			
Expt. N	lo.	List of Expe	riments						
1.		Perfo	rm basic oper	ations on ima	ages.				
2.		Perfo	rm histogram	equalization	•				
3.		Perfo	rm image filt	ering in spati	al domain.				
4.		Perfo	rm image filte	ering in frequ	ency doma	in.			

5.	Perform image compression using DCT / Wavelet transform.
6.	Perform edge detection using various masks.
7.	Perform global and adaptive thresholding.
8.	Apply morphological operators on an image.
9.	Perform basic operations on images.
10.	Perform histogram equalization.
11.	Perform image filtering in spatial domain.
12.	Design and Implementation of image processing based case study

1. Gonzalez and Woods, "Digital Image Processing", Pearson Education, 3rd edition

2. Iain E. G. Richardson, -H.264 and MPEG

3. Video Compression: Video Coding for Next Generation Multimedial, John Wiley and Son's Publication, 3rd Edition.

#### **Reference Books:**

1. A. K. Jain, Fundamentals of digital image processing, Prentice Hall of India, 1989.

2. Pratt William K. "Digital Image Processing", John Wiley & sons

3. A. Bovik, Handbook of Image & Video Processing, Academic Press, 2000

Program:B. Tech. (E&TC)					Semester: V				
Course: Antenna and Wave Propagation					Code: 5517				
Teaching Scheme Evaluat				Evaluati	ion Scheme				
Lecture	Tutorial	Credit	Hours	IE MTE ETE Total					
2		02	2	20 30 50 100					
<b>D'</b>									

Prior knowledge of

1.Electromagnetics. Is essential

#### **Objectives:**

- 1. To apply concept and properties of electromagnetism to obtain parameters of antennas.
- 2. To understand basic concepts and operating principles of antenna array.
- 3. To gain knowledge about HF and VHF, UHF antennas.
- 4. To identify appropriate antenna for specific application.

#### **Outcomes:**

After learning the course, the students should be able to:

- 1. Understand antenna basics, antenna parameters and types of antennas.
- 2. Design and analyze antenna array with different parameters.
- 3. Design various types of antennas.
- 4. Identify and analyze various types of antennas for specific applications.

Detail	cu Synabus.	
Unit	wave propagation mechanism	Duration
1	Antenna Basics: radiation mechanism, efficiency, directivity, beam efficiency, intensity, gain, power theorem and its application, radiation pattern, far field and near field, antenna aperture, effective height, bandwidth, VSWR, radio communication link, antenna impedance. Different types of antennas e.g., Microstrip patch antenna, Dipole antenna, array antenna, wire antenna etc	06
2	Antenna array: Concept of antenna arrays, Two element arrays and their directional characteristics, Principles of pattern multiplication & their application, Linear array analysis (uniforn antenna array), Broadside and end fire arrays. Array Antenna types: Yagi-Uda antenna, Aperture array, Slotted wave guide array.	06
3	<ul> <li>Wire Antennas - Dipole antenna, Short Dipole antenna, radiation resistance of short diploe antenna, folded dipole, Helix antenna, Loop antenna. Applications of all antennas.</li> <li>Reflector Antenna: Parabolic reflectors, Corner reflectors, Applications of all antennas.</li> <li>Aperature Anenna: Horn Antenna, Ultra-wideband antenna, MIMO antenna.</li> </ul>	06

4	Antenna for modern wireless communication: Antennas for Biomedical applications, Wearable antenna, Antennas for Terrestrial communication - mobile handsets and base station, vehicle to vehicle communication.	06
	Total Hrs.	24

1.C.A. Balanis, Antenna Theory - Analysis and Design, 2016, 3rd edition, Wiley & Sons, New York, USA.

2.K.D. Prasad ,"Antennas and Wave Propagation", Khanna or Satya Publications

#### **Reference Books:**

1. R.K. Shevgaonkar, "Electromagnetic Waves", TMH

2 Peter S. Hall," Antennas and propagation for body centric wireless communication", Artech house.

3 e book By Albert Sabban" Novel Wearable Antennas for Communication and Medical Systems", CRC press.

4. Albert Sabban, "Wideband RF Technologies and Antennas in Microwave Frequencies", 2016, Wiley, New York USA

"Knowlege Brings Freedom"

Antimism Excellence

Program: B. Tech. (E&Tc)					Semester :V				
Course: A	WP Lab				Code: BET5518				
Teaching S	cheme		-	Evaluation S	ı Scheme				
Lecture	Practica l	Tutoria l	Credi t	TW	OR	PR	Tota l		
Drior know	2hr/week		2	25	25		50		
1.Electromagnetics and uniform plane wave <b>is essential</b> .									
Objectives: 1.To Analyze radiation pattern of different antennas 2.To Evaluate VSWR at various conditions. 3.To Design and Simulate antenna using antenna simulation tools. 4.To Work in a team and learn modern tools Outcomes:									
At the end of 1.Analy 2.Evalu 3.To le 4.Desig	of Laboratory yze radiation p nate VSWR at arn modern to gn and Simulat uidelines: Any	work, the stup eattern of diffe various cond ols. <b>"Know</b> te antenna usi y Eight Expe	dents will be erent antenna itions lege Brin ng antenna s eriments is te	able to: as <b>gs Freedo</b> imulation tools o be performed	n)"				
			Deta	iled Syllabus:					
Expt. No.	List of Expe	eriments							
1	To Measure	Radiation pat	ttern, Return	Loss, Impedan	ce, Gain, Beam	width for Dip	ole Antenna.		
2	To Measure Radiation pattern, Return Loss, Impedance, Gain, Beam width for Folded Dipole Antenna.								
3	To Measure	Radiation pat	ttern, Return	Loss, Impedan	ce, Gain, Beam	width for Yag	gi Uda Antenna.		
4	To Measure	Radiation pa	ttern, Return	Loss, Impedan	ice, Gain, Beam	width for Ho	rn Antenna.		
5	To Measure Antenna.	Radiation pat	ttern, Return	Loss, Impedan	ce, Gain, Beam	width for Para	abolic Reflector		
6	Plot Standing Wave pattern and Measure SWR for open, short, and matched termination.								

7	MATLAB simulation of Broad side linear array with uniform spacing and amplitude
8	MATLAB simulation of End fire linear array with uniform spacing and amplitude.
9	Design Of Rectangular Microstrip Patch Antenna Using Strip Line Feed.
10	Design Of Rectangular Microstrip Patch Antenna Using Coaxial Feed.

#### **Reference Book:**

- 1. C.A. Balanis, Antenna Theory Analysis and Design, 2016, 3rd edition, Wiley & Sons, New York, USA.
- 2. K.D.Prasad ,"Antennas and Wave Propagation",Khanna or Satya Publications



Program	B. Tech.	(E&TC)				Semes	ter: V		
Course:	urse: Computational Tools for Data Analytic					<b>Code:</b> BET5519			
	Teac	hing Schem	e			Ev	aluation Sc	heme	
Lecture	Practical	Tutorial	Credit	Hours	IE MTE ETE Tota				
2	-	-	2	2	20	30	50	100	
rior Kn	owledge of:								
Ba	sic knowled	ge of MATL	AB and P	ython Prog	grammin	g is <b>essential</b>			
			IN NO	d h	Col	~			
Course O	bjectives: T	his course a	ims at ena	bling stude	ents to,				
	1.Apply th	e data analy	tics concep	pts using N	1ATLAE	and Python.			
	2 Demon	strate the an	nlicability	using stat	istical an	alveis of data	analytics		
	2. Demon		pheaonity	using stat	istical an	arysis of data	anarytics.		
	3. Graphic	al Analysis	using Dat	a Processi	ng and V	isualization.			
	4. Demons	strate the ba	sics conce	ept of Mac	hine Lea	rning.			
Course O	utcomes:		D Y	200			<u> </u>		
)n compl	etion of the (	course stude	ent will be	able to					
on compr		"k	nowled	ge Bring	gs Free	edom"			
	1. Demons	strate the da	ta analyti	cs concept	s using N	IATLAB and	Python.		
	2. Apply a	and Analyze	algorithn	ns using sta	atistical n	nethods			
3. Demonstrate the applicability of graphical analysis using Data processing and Visualization.									
	4. Underst	and and ap	<b>ply</b> the co	ncept of R	egressior	n, Classificati	on and clust	ering algorithms	
Detailed S	Syllabus:								
Unit D	escription							Duration	
1. <b>In</b>	troduction	to MATLAI	B & Pytho	on for Dat	a analyti	ics			
D	ata Analytics	Introduction	n Underst	anding the	data acc	essing data s	•t		
Int	troduction to	MATLAB	for Data	analytics:	MATL	AB libraries	for Data an	alvtics. 5	

importing & exporting data in MATLAB Introduction to Python for Data analytics:Python packages for Data science, importing & exporting data in Python

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2	Introduction to Statistical Methods					
2.	Introduction to Statistical Methods					
	Overview of statistical analysis, Introduction to descriptive statistics and data distributions. Visualizing Data Sets, Measures of Centrality and Spread, Distributions, Fit line to data-Linear Regression, Evaluating Goodness of Fit, Interpolate values from a data set-Linear Interpolation.	7				
3	Data Processing and Visualization					
5.						
	Overview of the content-Importing Hurricane Data, Getting Started with the Data,	5				
	Preprocessing data- Importing data from multiple files -Read large data stored in multiple	-				
	files using datastores - visualizing the multivariate data					
4.	Introduction to Machine Learning					
	Introduction to Machine Learning example and its applications,	7				
	Supervised Learning: Regression and Classification					
	Unsupervised Learning: Clustering, Reinforcement Learning					
	Total Hrs.	24				
Text F	Text Books:					
1.	Trevor Hastie, Robert Tibshirani, Jerome Friedman, "The Elements of Statistical Learn 2009.	ning", Springer				

2. Wes McKinney and O'Reilly, "Python for Data Analysis", 2nd Edition.

#### **Reference Books:**

- 1. EthemAlpaydin ,"Introduction to Machine Learning", Second Edition, MIT Press 2010.
- 2. Jake Vander Plas and O'Reilly, "Python Data Science Handbook: Essential Tools for Working with Data"
- 3. Joel Grus and O'Reilly, "Data Science from Scratch: First Principles with Python".

#### **Online courses**

- 1. <u>https://www.mathworks.com/academia/courseware/teaching-data-science-with-matlab.html</u>
- 2. https://swayam.gov.in/nd1\_noc20\_cs46/
- 3. https://onlinecourses.nptel.ac.in/noc21\_cs33/

Program: B. Tech. (E&Tc)						Semester:	V		
Course: Computational Tools for Data Analytics Lab						Code:BET	5520		
Teaching Scheme						Evaluation Scheme			
Lecture	Practical	Tutorial	Credit	Hours	TW	OR	PR	Total	
	2		1	2	25	25		50	

**Prior knowledge of:** 

Basic knowledge of MATLAB and Python Programmingis essential.

**Course Objectives:** This course aims at enabling students to,

1. **Apply** the data analytics concepts using MATLAB and Python.

2. **Demonstrate** the applicability using statistical analysis of data analytics.

3. Graphical Analysis using Data Processing and Visualization.

4. **Demonstrate** the basics concept of Machine Learning.

#### **Course Outcomes:**

On completion of the course, student will be able to

- 1. Demonstrate the data analytics concepts using MATLAB and Python.
- 2. Apply and Analyze algorithms using statistical methods
- 3. **Demonstrate the applicability** of graphical analysis using Data processing and Visualization.
- 4. Understand and apply the concept of Regression, Classification and clustering algorithms

General Guidelines: Any Eight Experiments is to be performed in MATLAB or Python					
Detailed Syllabus:					
Expt. No.	List of Experiments				
	Group A: Any 3 Experiments are Compulsory				
1	Introduction to Python Programming				
2	Perform different measures of central tendency on data set with Python				

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3	Implement data exploration and visualization with Python							
4	Implement Linear regression analysis for housing prices dataset using Python							
	Crown B: Any 3 Experiments are Compulsory							
	Group D. Any 5 Experiments are Compulsory							
5	Introduction to MATLAB Programming							
6	Perform different measures of central tendency on data set with MATLAB							
7	Implement data exploration and visualization with MATLAB							
8	Implement Linear regression analysis for housing prices dataset using							
	Group C: Any Two Experiments are Compulsory							
9	Implement classification using Support Vector Machine (SVM) for binary class using Python or MATLAB							
10	Implement Sensor data collection through smart phone and processing data with MATLAB							
11	Implement temperature data capturing and prediction using curve fitting with MATLAB							
<b>Text Books:</b>								
<ol> <li>Trevor Spring</li> <li>Wes M</li> </ol>	<ol> <li>Trevor Hastie, Robert Tibshirani, Jerome Friedman, "The Elements of Statistical Learning", Springer 2009.</li> <li>Wes McKinney and O'Reilly, "Python for Data Analysis", 2nd Edition.</li> </ol>							
<b>Reference Bo</b>	oks:							
1. Eth	emAlpaydin,"Introduction to Machine Learning", Second Edition, MIT Press 2010.							
2. Jak	e Vander Plas and O'Reilly, "Python Data Science Handbook: Essential Tools for Working							
wit	with Data"							
3. Joe	I Grus and O'Reilly, "Data Science from Scratch: First Princip les with Python".							
Online course	es							
I. <u>htt</u>	os://www.mathworks.com/academia/courseware/teaching-data-science-with-matlab.html							
2. http	ps://swayam.gov.in/nd1_noc20_cs46/							
3. htt	3. https://onlinecourses.nptel.ac.in/noc21_cs33/							

# **Open Elective-II**

Program:B. Tech. (E&TC)					Semester: V				
Course:S	mart City: An	Electronic F	Perspective		Code: BET5601				
Teaching	Scheme			Evaluation Scheme					
Lecture	Tutorial	Credit	Hours	IE	MTE	ETE	Total		
3	-	3	3	20	30	50	100		
Prior kno	owledge of								
1 Bas	sic Electronics								
2. Bas	2. Basics of electronic communications. Is essential.								
Objectives:									
1 To		and heating	f and at	and from d		at a flot			
1. 10 2. To	explore need a	and basics o	I smart cit	y and fund	lamental conce	epts of 101.			
2. 10 3 To	enuclidate the r	oles of sens	ors and pro	d network	101				
Outcome	s.				ing protocols.				
Jucome									
Af	ter learning the	e course, the	students v	vill be able	e to:				
1 roo	lize the need o	f amort aitu	and its im	nlomontat	ion challonged				
1.1ea	mprehend the	various con	cents term	inologies	and architectu	re of IoT system	me		
2. CO 3. Us	e sensors and a	octuators for	design of	Intrologics	n for smart cit	v			
$\frac{5.05}{4}$ An	only various wi	reless prote	cols for de	esign of Io	T systems	y			
5 Ide	entify the impa	ct of distrib	uted Intelli	gence and	Central Plann	ing on city			
6. De	sign IoT frame	work based	applicatio	ns used in	smart city.	ing on only.			
Detailed S	Syllabus:								
II:4 T	Degemintion	"Kŋo	wlege E	srings l	reedom"		Duration		
Unit	Description						Duration		
1	Nagassity of S	MADT CI	TV. The	Smort Cit-	Dhiloconhy	Davalonmant			
	of Asian Cities	Megacitie	s of India	· Current (	Thallenges Th	e India Story			
	of Smart Citie	s Concent	ual Basis	of a Smal	t City Globa	l Smart City	06		
	Programs Rec	ommendati	ons for Sm	art City F	ramework	i Sinart City	Vo		
2					anie work.				
	Fundamental	s of IOT:	History (	of IoT, I	ntroduction, d	efinition and			
	characteristics	of IoT, arch	intecture of	IoT, Phys	ical & logical	design of IoT,	06		
	Enabling tech	noiogies in	ioi, idei	numers in	101,M2M CO	munication			
2	verses 101.								
3	Sensor Netwo	orks:Definit	tion, types	of sensor	s & actuators	, examples &	06		
	working, RFII	O Principles	and comp	oonents, W	/i-Fi, Bluetoot	h, etc. ireless	VU		
	sensor network	k: History, s	ensor node	e, network	ing nodes, WS	N versus IoT.			

4	Wireless Protocols for Smart Cities: IPv6overLow-Power Wireless Personal Area Network: Features, Addressing, Packet fragmentation, Operation, Security. ZigBee: Architecture Objectives, Wireless NetworkingBasics, Wireless Networking Assumptions, Bluetooth Low Energy, IoT data protocols: MQTT Protocol. COAP Protocol, AMQP Protocol.	06				
5	Distributed Intelligence and Central Planning.					
	On the Interplay between Humans and Smart Devices, Theoretical Tools, Intelligence-artificial Intelligence (Machine Intelligence), Information Dynamics, Synergetic, Information Dynamics and Algometry in Smart Cities.	06				
6	Applications of IoT in smart city: TheRoleof ICTs.					
	Applications in smart city & their distinctive advantages -smart environment, smart street light and smart water & waste management. Smart transportation and hospitality, Roleand scopeofIOT inpresent andfuturemarketplace. Industrial IoT.	06				
	Total Hrs.	36				
Text ]	Books:					
1. 2. 3. 4. <b>Refer</b>	<ol> <li>Surjeet Dalal ,Vivek Jaglan "Green Internet of Things for Smart Cities: Concepts, Implications, and Challenges", CRC Press; 1st edition.</li> <li>Sudip Misra, Anandarup Mukherjee, Arijit Roy, "Introduction to IoT" Cambridge University Press.</li> <li>HakimaChaouchi, "TheInternetofThingsConnectingObjectstotheWeb"ISBN:978-1-84821- 140-7, Wiley Publications</li> <li>OlivierHersent, DavidBoswarthick, andOmarElloumi, "TheInternetofThings:KeyApplications and Protocols", Wiley Publications</li> <li>Reference Books:</li> </ol>					
1.	Vincenzo Piuri, Rabindra Nath Shaw, "AI and IoT for Smart City Applications" 1st ed. 2022 edition.	,Springer;				
2.	Alfredo Barton, Raymond Manning, "Smart Cities:Technologies, Challenges a Prospects" Nova Science Pub Inc	nd Future				
3.	Ibrahim El Dimeery, Moustafa Baraka, Syed M. Ahmed, "Design and Construc Cities" Amin Akhnoukh, Springer; 1st ed. 2021 edition	ction of Smart				
4.	Ricardo Armentano, Robin Singh Bhadoria ,Parag Chatterjee , "The Internet of Things: Foundation for Smart Cities", eHealth, and Ubiquitous Computing" Chapman and Hall/CRC; 1st edition					
5.	DanielMinoli, "BuildingtheInternetofThingswithIPv6andMIPv6:TheEvolvin MCommunications", ISBN: 978-1-118-47347-4, WillyPublications	ngWorldofM2				
6.	PethuruRajandAnupamaC.Raman,"TheInternetofThings:EnablingTechnologies dUseCases",CRCPress	s,Platforms,an				
Online	Link/Courses:					

1. <u>http://www.cse.wustl.edu/~jain/cse570-15/ftp/iot_prot/index.html</u> 2. https://onlinecourses.nptel.ac.in/noc17_cs22/course								
Program:	B. Tech. (E&	TC)	hwad		Semester: V			
Course: M	Iodeling and S	Simulation			Code: BET5	602		
Teaching	Scheme	8		<b>Eval</b> uati	on Scheme	3		
Lecture	Tutorial	Credit	Hours	IE	MTE	ETE	Total	
3	E	3	3	20	30	50	100	
Prior knov	wledge of					90		
1. Eng	ineering Math	ematics essential						
<b>Objectives</b>	s:	"I/po	wlogo E	Pringe E	'roodom"			
1. To exp	lain basic mod	deling techn	iques and	tools.	reedon)			
2. To den	nonstrate role	of Model in	continuou	is and disc	rete systems.			
4. To illu	strate with fuz	zy set and i	ts modelin	ig.				
Outcomes	•		Sip	Ce 1999				
After learn	ing the course	e, the studen	ts should l	be able to:				
1. Unders	stand the basic	c requireme	nts of Mo	deling and	tools used in s	simulation		
2. Analyz	the physical	l models an	d their crit	teria as per	knowledge of	the system	1.	
3. Compa	3. Compare different types of deterministic models and their applications.							
4. Use op 5. Design	the Neural Ne	etwork base	d models	using appr	opriate softwar	n. e tools.		
<ol> <li>Design the rectual rectivery based models using appropriate software tools.</li> <li>Design and simulate the Fuzzy controllers to solve engineering problems.</li> </ol>								
Detailed S	yllabus:							
Unit D	escription						Duration	

1	<b>Introduction:</b> Programming environment, input and output variables, State variables, basic syntax; Deterministic linear model, Array mathematics in Matlab, Plotting, Static and Dynamic systems; Hierarchy	
	of knowledge about a system and Modeling Strategy.	06
2	<b>Physical Modeling:</b> Dimensions analysis, Dimensionless grouping of input and output variables of find empirical relations, similarity criteria and their application to physical models. Stochastic modeling, Review of conservation laws and the governing equation for heat, mass and momentum transfer.	06
3	Modeling of System with Known Structure: Deterministic model: distributed parameter models in terms of partial identification and their solutions and lumped parameter models in terms of differential and difference equations, state space model, transfer functions block diagram and sub systems, stability of transfer functions, modeling for control.	06
4	<b>Optimizations and Design of Systems:</b> Summary of gradient based techniques : Nontraditional Optimizations techniques, genetic Algorithm (GA)- coding, GA operations, elitism, Application using MATLAB: Simulated Annealing, Introduction to GUI,GUI Programming.	06
5	Introduction to Neural Network Modeling: Basics of Neural Network, Neural Network Modeling of Systems only with Input-output Database: Neurons, architecture of neural networks, knowledge representation, learning algorithm. Multilayer feed forward network and its back propagation learning algorithm,	06
6	<b>Modeling Based on Expert Knowledge</b> : Fuzzy sets, Membership functions, Fuzzy Inference systems, Expert Knowledge and Fuzzy Models, Design of Fuzzy Controllers, Simulation of Engineering Systems: Monte-Carlo simulation, Simulation of continuous and discrete processes with suitable examples from engineering problems.	06
	Total Hrs.	36

- 1. Zeigler B.P. Praehofer. H. and Kim I.G. "Theory of modeling and simulation", 2 nd Edition. Academic press 2000
- 2. Jang J.S.R. sun C.T and Mizutani E,, "Neuro-Fuzzy and soft Computing ", 3 rd edition, Prentice hall of India 2002

#### **Reference Books:**

- 1. Steven I Gordon. Brian Guilfoos."Introduction to modeling and simulation using MATLAB & Python" CRC press.
- 2. Dr.Shailendra Jain." Modeling and simulation using MATLAB-Simulink ",2 nd Edition,Wiley
- 3. Shannon, R. E., "System Simulation: the Art and Science", Prentice Hall Inc. 1990
- 4. Pratab.R " Getting started with MATLAB" Oxford university Press 2009

**Online course link:** https://in.mathworks.com/learn/training/simulink-fundamentals.html



# **Proficiency Courses**

Progr	Program: B. Tech. (E&TC) Semester: V/VI							
Cours	se: Basics	of LabVIEW		Code: BET5911/ BET6911				
	Teach	ing Scheme		Evaluation Scheme				
Prac	tical Tutor	ial Credit	Hours	тw	OR	PR	Total	
2		-	2	-	-	-	-	
<b>Prior k</b> 1. 2.	<b>knowledge of:</b> Basics of progr Electronics De	amming vice and Circu	itschwod	Co	llegeor			
Objec	scillal. rtives:	5			The	5		
1.T	o introduce to s	students, the fu	indamental com	ponents of	LabVIEW V	virtual Instrume	nts	
2. T	o demonstrate	features of Lab	VIEW with im	plementatio	n of basic at	polication.	iii.	
Outco	mes:				n or ousic u			
After	completion of t	nis course, the	students will be	e able to.				
1.	Understand the	applications of	of LabVIEW Vi	rtual Instru	nent			
2.	Build basic Vin	tual Instrumer	t for an applica	tion.				
	in.		Detailed	l Syllabus		- 10 - 10 - 10 - 10 - 10 - 10 - 10 - 10		
Unit	Description	"k	nowlege B	rings Fre	eedom"		Duration (H)	
1	Introduction		Progress Cred	ibility Conf	idence			
	Features of Virtual Instrumentation with LabVIEW, LabVIEW Installation, LabVIEW Environment Basics, Fundamental Tools, Debugging tools, Graphical Programming, Execution Structures						08	
2	Programmin	g Component	s in LabVIEW	8 10				
	Data Structure	es in LabVIEW	V, Passing Data	Between Le	oop Iteratior	ns in	08	
	LabVIEW Lo	ops and Charts	s – For, While,	Charts, Mul	tiplots, Wiri	ng Data into	00	
	Charts Building	ng LabVIEW V	VI application f	or paramete	r conversior	1.		
3	Introduction	to Data Acqu	isition in VI					
	VI Applicatio	n- Implementa	tion of Data Ac	equisition S	ystem for		08	
	Temperature	neasurement						
						Total	24	

#### **Reference Books:**

- 1. Jeffrey Travis, Jim Kring, "LabVIEW for Everyone", Pearson Education, Third edition-2006
- 2. Gary W. Johnson, Richard Jennings, "LabVIEW Graphical Programming", McGraw-Hill Education, Forth Edition-2006
- 3. Behzad Ehsani, "Data Acquisition using LabVIEW", Packt Publishing, First edition- 2016
- 4. Marco Schwartz, Oliver Manickum, "Programming Arduino with LabVIEW", Packt Publishing, First edition-2015



Program:	a: B. Tech. (E&TC)				Semester	·: V/VI		
Course:	MATLA	MATLAB Scripting				BET5912/	BET6912	
Teaching Scheme					<b>Evaluation Scheme</b>			
Practical	Tutorial	Credit	Hours	TW OR PR Tot			Total	
2	-	-	2	-	-	-	-	

#### Prior knowledge of:

- 1. Engineering Mathematics
- 2. Software operational skills

#### is essential.

#### **Objectives:**

- 1. To promote new teaching model that will help to develop programming skills and technique to solve mathematical problems.
- 2. To use MATLAB as a simulation tool.

#### **Outcomes:**

After learning the course, the students should be able to:

- 1. Learn the MATLAB interface and various methods
- 2. Build a program in MATLAB for implementing desired application or solving a mathematical equation.
- 3. Create a GUI application using MATLAB
- 4. Implement the given algorithm and simulate in MATLAB.

## **Detailed Syllabus:**

Unit	Description	Duration
1.	Introduction to MATLAB The MATLAB Environment, MATLAB Basics – Variables, Data types, Operators, Expressions, Input and output, Vectors, Arrays – Matrices, MATLAB Functions, Built-in Functions, User defined Functions, Aabstraction and encapsulation	06
2.	Programming with MATLAB	06

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	Conditional Statements, Loops, MATLAB Programs – Programming and Debugging, Profiling Tools and Report Generation, Applications of MATLAB Programming, GUI Development in MATLAB.	
3	<b>Graphics with MATLAB</b> Files and File Management – Import/Export, Basic 2D, 3D plots, Graphic handling, parametric plots, contour lines and implicit plots, field plots, multiple graphics display function, multivariate data, data analysis	06
4	Mathematical Computing with MATLAB Polynomials, Curve fitting, Interpolation, solving algebraic equations, Differentiation, Integration, Basic Symbolic Calculus and Differential equations, Solving an ordinary differential equation, Numerical Techniques and Transforms.	06
	Total	24
Text I	Books:	
1.	S. I. Chapman, MATLAR Programming for Engineers Thomson A <sup>m</sup> edition 20	
	5. 5. Chapman. WATEAD Trogramming for Engineers. Thomson, 4 Control 20	16.
2.	C. F. Van Loan. Introduction to Scientific Computing. Prentice Hall, 2 <sup>nd</sup> edition	, 2000.
2. Refere	C. F. Van Loan. Introduction to Scientific Computing. Prentice Hall, 2 <sup>nd</sup> edition	, 2000.
2. <b>Refer</b> 1.	C. F. Van Loan. Introduction to Scientific Computing. Prentice Hall, 2 <sup>nd</sup> edition ence Books: C. B. Moler, Numerical Computing with MATLAB, Cengage Learning, Edition	116. , 2000. :: 2012.
2. <b>Refer</b> 1. 2.	C. F. Van Loan. Introduction to Scientific Computing. Prentice Hall, 2 <sup>nd</sup> edition ence Books: C. B. Moler, Numerical Computing with MATLAB, Cengage Learning, Edition D. J. Higham and N. J. Higham. MATLAB Guide. Siam, 2 <sup>nd</sup> edition, 2005.	, 2000. .: 2012.

Program: B. Tech. (E&TC)				Semester: V/VI				
Course: Embedded Product Design					Code:	BET5913/ E	BET6913	
Teaching Scheme				Evaluation Scheme				
Practi	cal Tutorial	Credit	Hours	TW	OR	PR	Total	
2	-	-	2	-	-	-	-	
<b>Prior</b> 1. 2	Prior knowledge of: 1. Basic electronics, Printed circuit board design.							
is e	essential.	oning and ob,			999 990			
Objec 1. 2. Outco After 1 1. 2. 3.	Objectives:         1. To make students aware of embedded product development process.         2. To impart knowledge and skills required for embedded product development.         Outcomes:         After learning the course, the students should be able to:         1. Learn the fundamentals of embedded product development.         2. Learn about the hardware elements of embedded product.							
4.	Design, test and d	ebug embedo	led product.	ibility Con	fidence			
			Detailed	Syllabus:	10 A			
Unit	Description		Sipe	e 1999			Duration	
1.	Fundamentals of Embedded Product development       Characteristics and quality attributes (Design Metric) of embedded system, Safety and reliability, ethical practice, real time system's requirements, real time issues.       06							
2.	Hardware Eleme Core of the em Actuators, Com Solar), PCB and I	ents of Embe abedded syst nunication I Passive comp	edded Produ tem, Microo interface, Po onents.	uct controller, ower-supp	Memory, ly (Battery	Sensors and technology,	06	

	Software Elements of Embedded Product	
3.	Program Modelling, Embedded C-programming concepts, Embedded firmware (RTOS, Device drivers, Application programs).	06
	System Integration, Testing and Debugging Methodology	
4	Embedded Product Design Life Cycle (EDLC), Hardware Software Codesign Testing & Debugging, Blackbox testing, White Box testing, Hardware emulation, Logic analyzer.	06
	Total	24
Text I	Books:	
1.	Frank Vahid and Tony Givargis, - Embedded System Design - A Unifi	ed hardware/
	Software introduction, 3rd edition, Wiley, 2006.	
2.	Karl Ulrich, Steven Eppinger, "Product Design and Development", McGraw H	ill / Irvin, 3rd
	Edition 2009.	
3.	Parag H Dave, Himanshu. H. Dave, Embedded systems: Concepts, design and p	programming,
	Pearson India, 2015	
Refere	ence Books:	
1	K.V. Shibu, "Introduction to Embedded Systems", McGraw Hill Education	India Private
	Limited, 2nd Edition, 2017.	
2.	Ajay Deshmukh, "Microcontrollers Theory and Applications", TATA McG	raw Hill, 4th
	Edition, 2005.	
3.	Raj Kamal, —Embedded Systems – Architecture, Programming and Design" 3 <sup>r</sup>	<sup>d</sup> edition,
	2014 Optimism Excellence	

Progra	am:	B. Tech. (E&TC) Semester: V/VI						
Cours	e:	Model-Bas	5914/BET6914					
		Teaching	Scheme			Evalua	tion Scheme	
Pract	ical	TutorialCreditHoursTWORPRTo						
2		-	-	2	-	-	-	-
Prior 1. 2. 3. is o Object 1. 2.	<ul> <li>Prior knowledge of: <ol> <li>MATLAB environment</li> <li>Control Systems</li> <li>Embedded System Design </li> <li>is essential.</li> </ol> </li> <li>Objectives: <ol> <li>To make students aware of Model Based Development.</li> <li>To impart knowledge of MATLAB and Simulink</li> </ol> </li> </ul>							
Outco After l	Outcomes: After learning the course, the students should be able to:							
1.	Use	Design of E	xperiment n	nethods to cre	eate models	of physical	systems.	
2.	App	ly basic cont	rol algorith	ms to a real p	hysical system	em.		
3.	Com	nect compon	ent models	together to m	nodel a large	r more com	plex system.	
4.	Depl	oy a control	algorithm	on a real-time	e target.			
				Detaile	d Syllabus:			
Unit	Des	cription						Duration
1.	Auto	omotive Co	ntrol Syste	ms				06

	Analog and digital control methods, Modelling of linear systems, System	
	responses, Introduction to Automotive Control Systems and Model Based	
	Development.	
	Development in MATLAB environment	
2.	Introduction to MATLAB, Simulink and SIMSCAPE tool boxes, Model-	06
	Based Design for a small system: Motor Model, Generator Model, Controller	
	Model.	
	Tuning and Refining Models	
2	SimDriveline Introduction, Exploring the system response using different	06
2.	control methods, Tuning the system, exploring system limitations, Modelling	
	and simulation of Automotive Systems with simple examples.	
	Real time implementation of MBD	
4	Real time simulations on a simple target (Arduino / Raspberry Pi etc), Plant	06
	on Real-Time Target like Freescale, Infineon, etc. Display Performance on	
	Virtual Gauge Display.	
	Total "Knowlege Brings Freedom"	24
Text l	Books:	
1.	Shailendra Jain, Modeling and Simulation using MATLAB - Simulink, 2editoin	n, 2015.
2.	Agam Kumar Tyagi, Matlab and Simulink for Engg, Oxford, 2011.	
Refer	ence Books:	
1.	Eshkabilov Sulaymon L., Practical MATLAB Modeling with Simulink, APress	,
2.	Wu Wei, Model-Based Design for Effective Control System Development, IGI	Global
3.	Zander, Schieferdecker, Mosterman, Model-Based Testing for Embedded S	systems, CRC

Press, Inc., 2012.

Progra	Program: B. Tech. (E&TC)					V/VI		
Cours	e: PCB Design	Code:	BET5915/BET	6915				
Teaching Scheme					Evalu	ation Scheme		
Pract	ical Tutorial	Credit	Hours	TW	OR	PR	Total	
2	-	-	2	-	-	-	-	
<b>Prior</b>	knowledge of:		d				-	
1.	Basic understand	ing of electro	onic devices a	nd circu	its, Digital Ele	ectronics		
is esse	ntial	(chin			2°0,			
Objec	tives:							
1.	To make students	s aware of va	arious hardwa	re and a	software tools	used for circui	t simulation,	
	PCB design and f	abrication.						
	/b							
2.	To impart in-dept	th practical sl	kills required	for the c	levelopment o	f PCB.		
Outco	Outcomes:							
After l	earning the course	, the students	s should be ab	le to:	Freedom"			
1.	Identify Electroni	ic Componen	ts Symbols &	Footpr	ints			
2.	Construct Compo	onent librarie	s & use them	effectiv	ely			
3.	Create a schemati	ic of an analo	og and digital	circuit				
4.	Simulate schemat	tic and design	n a Printed cir	cuit boa	ard for it.			
			Detailed S	Syllabus	5:			
Unit	Description						Duration	
	Introduction to	Electronic	Circuit Simu	lation a	and PCB: Ba	sics of circuit		
	simulation, Elect	rical rules, P	CB design rul	les for v	various applica	tions, various		
1.	open source and	commercial l	EDA tools for	circuit	design, simula	tion and PCB	06	
	design							

	PCB Design software:							
2	Schematic Entry, Netlist Creation, Component libraries, Design of Boards,	06						
2.	Layout of Parts, Optimizing Parts Placements, Pads and Via, Manual and Auto	00						
	Routing, Handling Multiple Layers, Gerber files.							
	Electromagnetic Interference.: Overview of Electromagnetic Interference and							
2	Electromagnetic Compatibility, Reduction techniques for EMI, Line Impedance	07						
3.	Stabilization Network (LISN), Conducted Noise, Common Mode Noises (CM),							
	Differential Mode Noises (DM), EMI filter Design							
	<b>Understanding the manufacturing process of PCB</b> : Overview of various PCB							
4	manufacturing machines, post-processing methods, Study of soldering defect							
-	and rectification, Advanced technologies in Manufacturing, assembly and							
	soldering.							
	Total	24						
Text 1	Books:							
1.	Bossart, Printed Circuit Boards: Design and Technology, Tata McGraw Hill, 200	)2.						
2.	Farid N. Na <mark>zm,</mark> Circuit Simulation, Wiley-IEEE Press, 1 <sup>st</sup> edition, 2010.							
Refer	ence Books:							
1.	1. Franco, Design with Operational Amplifiers & Analog Integrated Circuits. Tata McGraw Hill.							
	3 <sup>rd</sup> Edition, 2002.							
2.	Horowitz & Hill, The Art of Electronics; Cambridge University Press, 3rd edition	n, 2015.						
3.	Mitzner.K, Complete PCB Design Using Orcad Capture and Layout. Elsevier	Newnes, 1st						
	edition, 2007.							